

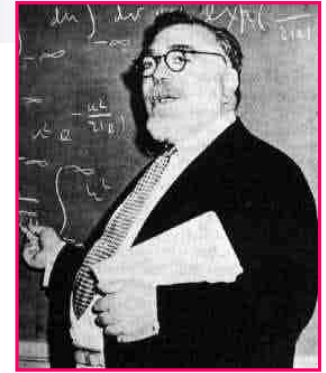
Opportunities at the interface of signal processing and stochastic eigen-analysis

Arthur B. Baggeroer & Raj Rao
Dept. Electrical Engineering
and Computer Science
MIT

Outline

- Covariance based methods
 - “Array” signal processing
- Beamforming
 - The role of random matrices
 - “Classical” Capon beamforming algorithm
- Opportunities for collaboration
- The art of adapting theory to practice
 - Importance of “wobble room”
- Some mathematical questions

Covariance based methods



- Correlation techniques = foundation of signal processing
 - From theory (*Wiener, et.al*) to practice
 - "... the potential significance of **correlation techniques** had fired the imagination the general enthusiasm was due to experimental evidence that **weak signals could be recovered in the presence of noise by using correlation techniques**. From that point the field evolved very rapidly." -- Professor [Henry J. Zimmermann](#), MIT RLE Director, 1958.
- Covariance based methods extended to array processing

Task	Example
Detection	Is a plane present?
Estimation	Location of plane
Classification	What kind of plane?

Taxonomy of Array Processing Problems Which Use Random Matrices

■ Beamforming

- Objective: Output Time Series

- Examples

- Digital Communications => satellites, land links
- Post processing for radar, sonar, seismics, e.g. synthetic aperture and other doppler based imaging methods

■ Directional spectrum estimation

- Objective: Estimate distribution of power *versus* k - ω or angle(s) - (waveform or signal function not needed)

- Examples

- Ambient noise for sonar, radio astronomy
- Sea surface wave spectra, seismicity

Taxonomy of Array Processing Problems Which Use Random Matrices (cont)

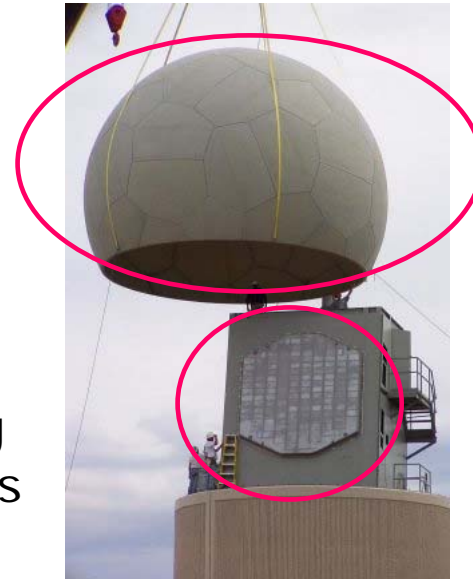
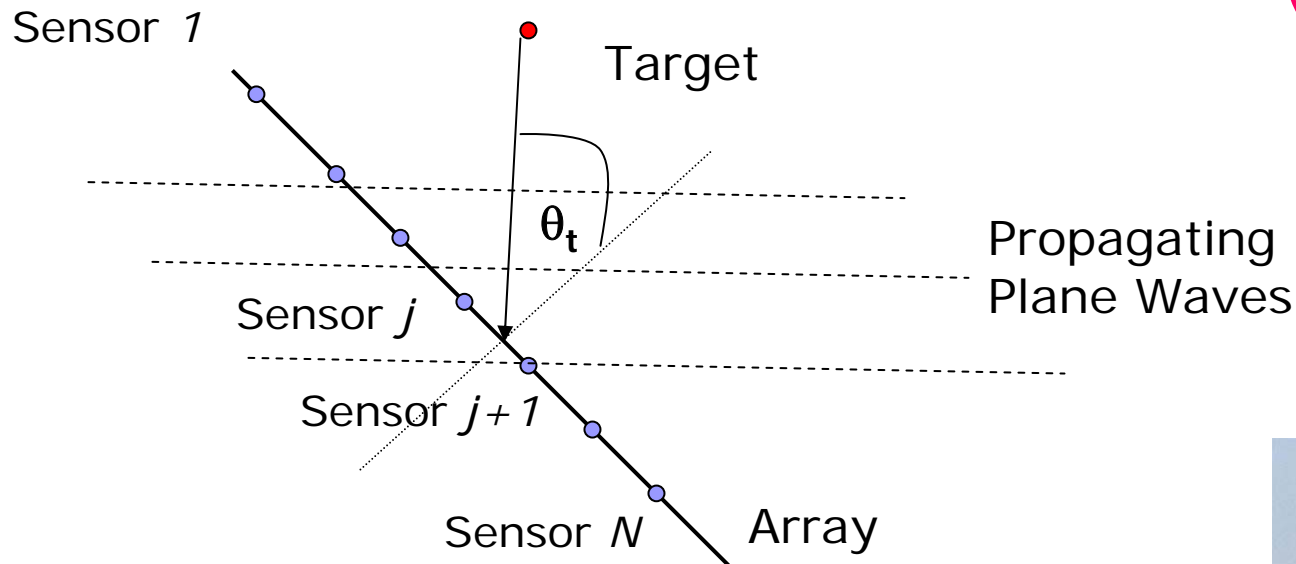
- Directional of Arrival Estimation
 - Objective: Estimate angles for a set of signal emitters
 - Examples
 - source localization (power irrelevant)
 - tracking (localization *versus* time)

Array processing applications

- Wireless communications
 - e.g. Multiple antennas (“MIMO”) in routers
 - e.g. Cellphone radio towers
- Biomedical imaging
 - MEG
- Emerging applications
 - Targeted therapy for lesions



“Array” Signal Processing



- “Array” = Sensors placed together
- Main idea: Adding sensors (generally) enhances capabilities
 - Example: Human ear (at high frequencies)
- Many geometries (often concurrently)
- **Built on the mathematics of correlation techniques!**

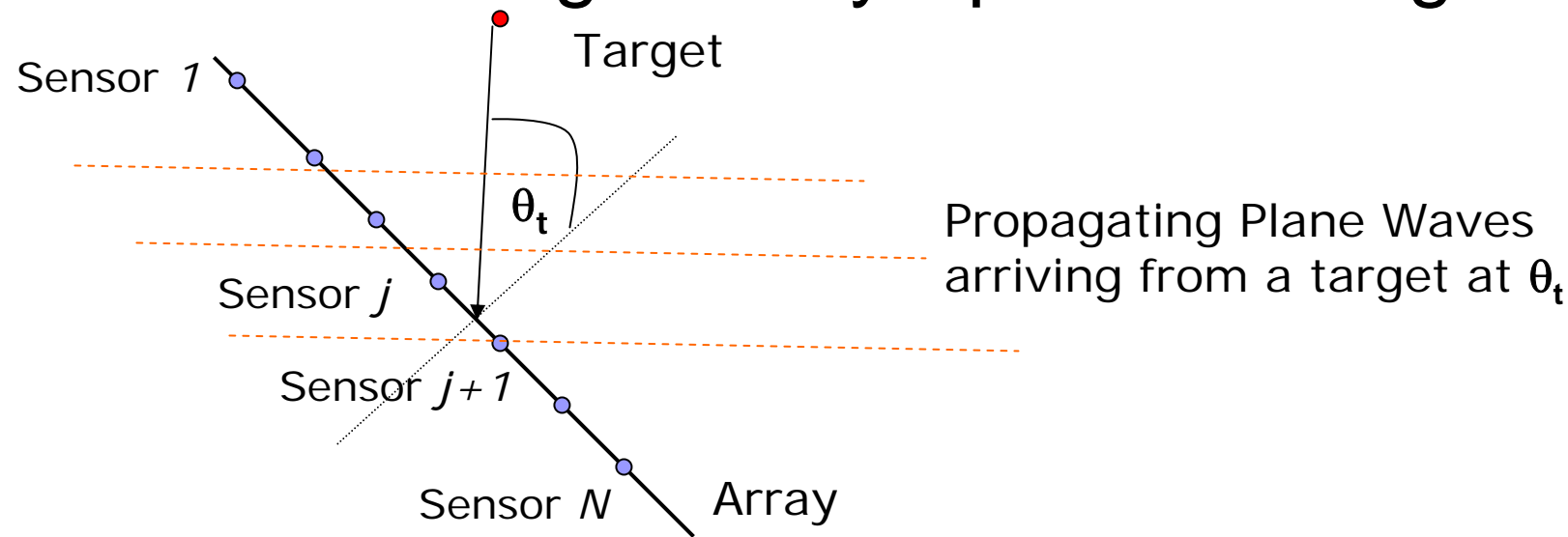
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 - “Classical” Capon, or Minimum Variance, Distortionless Response (MVDR) processing
 - Many variants, but most involve

$$w = \alpha \hat{R}^{-1} \hat{s}$$

- w / \hat{R} the sample covariance matrix and \hat{s} the steering “replica” vector
- to practice
 - Importance of “wobble room”
- Some mathematical questions

Beamforming = Array Spatial filtering



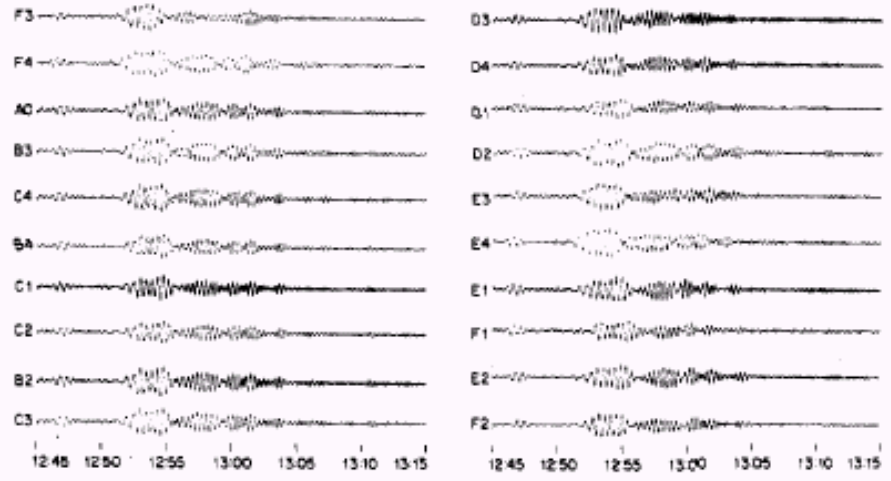
- **Idea:** Measurement @ time t at sensor j is **correlated** with Measurement @ time $t+\Delta t$ at sensor $j+1$. Hence exploit this relationship!
- **Physics:** Δt and the degree of correlation depends on
 - Array geometry (placement of sensors)
 - Propagation physics (air vs. water or sediment, free space vs. dispersive, linear vs. nonlinear)
 - Multiple targets and randomness add/create the challenge.



Capon 1969

Capon beamformer for Seismic Signal Processing

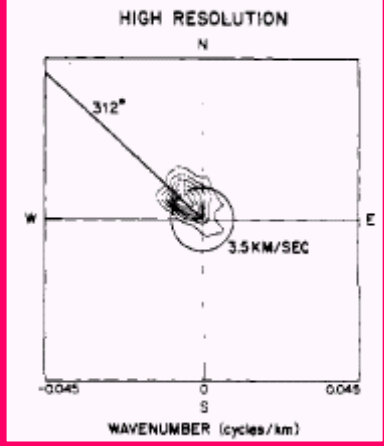
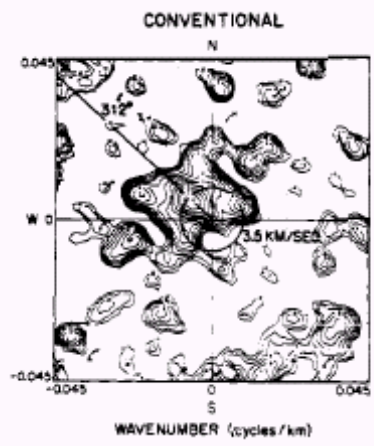
Array signals, replicas $S(\theta, \phi)$, power estimates



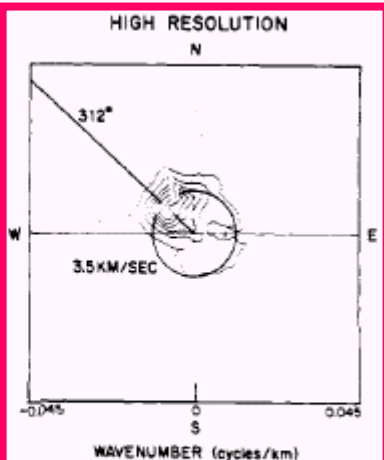
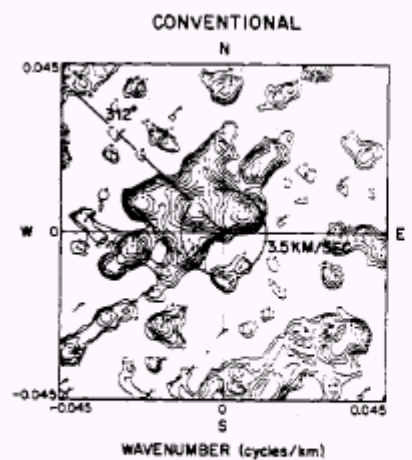
21 NOV 66
KURILE ISLANDS EVENT

Fig. 6. The long-period waveforms for 21 November 1966 Kurile Islands event.

Capon: High-Resolution Frequency-Wavenumber Spectrum Analysis, 1969. (Two figures indicate time changing paths and refraction of continental margins)

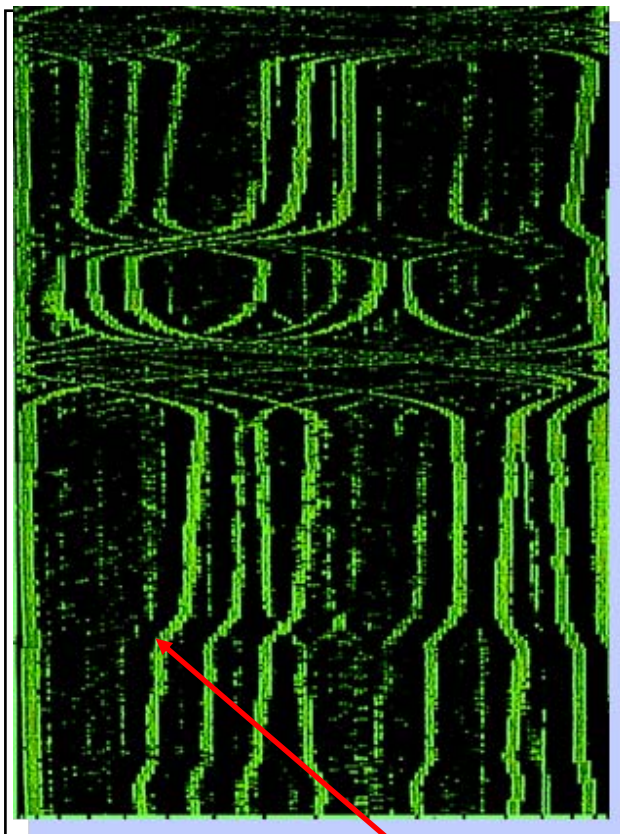


FREQUENCY = 0.03 Hz
(a)
21 NOV 66
KURILE ISLANDS EVENT

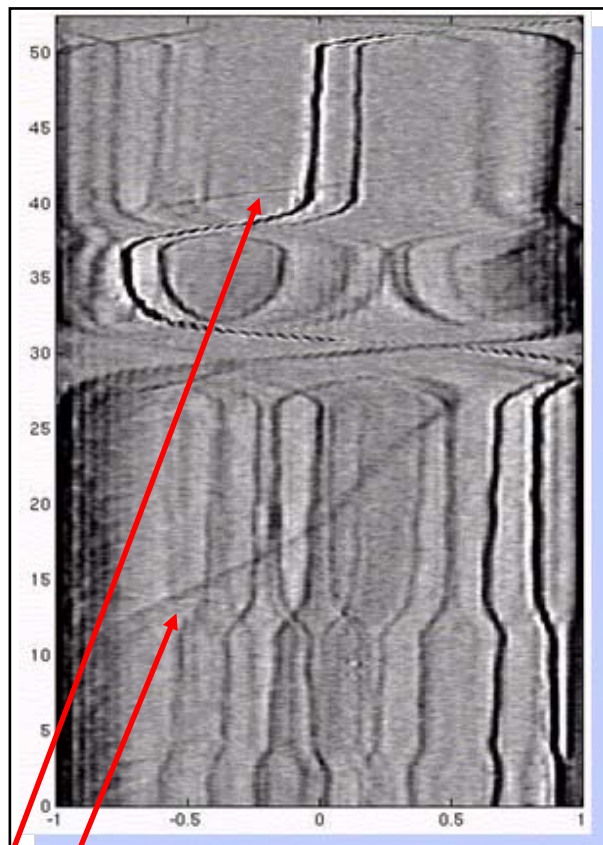


FREQUENCY = 0.04 Hz
(b)
21 NOV 66
KURILE ISLANDS EVENT
12:40:00 TO 13:40:00

APB-98/ARCI Phase 2: Signal Processing and OMI Gains



Legacy Display



A-RCI - 2

Contact

Vs.

No Contact

ARCI-2 Leveraged
Advanced BB
Algorithms:

- VLF Emphasis
- Sub Band Peak Energy Detect & SCOT (Adaptive Equalize)
- Cross-Correlation for Improved Bearing Resolution & Detection

BQQ-5 + AFTAS
Uses Legacy LR &
CC with Fixed
Spectral Shaping

Array Snapshot Processing

$$\mathbf{x} = \mathbf{z} + \mathbf{w}$$

Snapshot Signal Noise

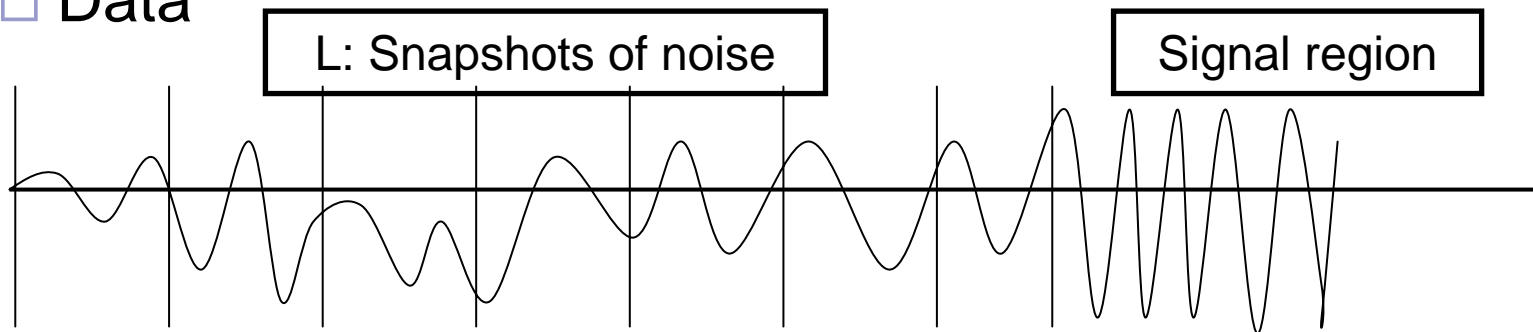
- \mathbf{x} is the $N \times 1$ “snapshot” vector collected at a single time instant
- \mathbf{x} is modeled as multivariate (complex) Gaussian
- $E[\mathbf{x} \mathbf{x}^H] = \mathbf{R} = \underline{\text{True Covariance Matrix}}$
- True Covariance Matrix encodes:
 - Spatial correlation of measurements due to ALL the targets
 - Effect of random noise field
- In practice use Sample Covariance Matrix (\mathbf{R}^{\wedge}) instead

Array Snapshot Training Problem

□ Sample Covariance

$$\hat{R} = \frac{1}{L} \sum_{l=1}^L x^l x^{lH}$$

□ Data



Array Snapshot Training (cont)

- L (# of snapshots) often \ll N (# of sensors)
 - Do not want signal in noise sample covariance estimate \Rightarrow self nulling of the desired signal
 - OK for spectral estimation problems, but Capon estimator is for power, not power density
 - Sources of limit on L
 - Non stationarity (source motion through resolution cell)
 - Array transit time and coherent relative phase addition over bandwidth

Direction of Arrival Estimation

- K targets located at $\theta_1, \theta_2, \dots, \theta_K$: **Canonical radar problem**

- If \mathbf{R} is known a priori

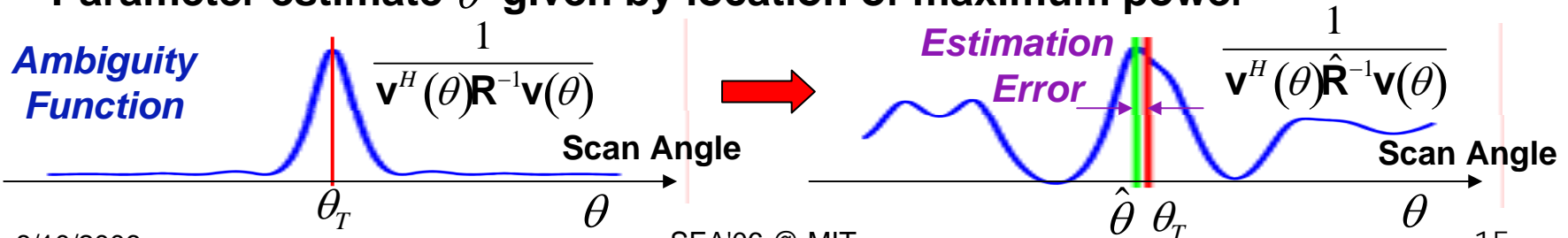
$$P_{\text{Capon}}(\theta) = \frac{1}{\mathbf{v}^H(\theta)\mathbf{R}^{-1}\mathbf{v}(\theta)}$$

- If \mathbf{R} is estimated

$$\hat{P}_{\text{Capon}}(\theta) = \frac{1}{\mathbf{v}^H(\theta)\hat{\mathbf{R}}^{-1}\mathbf{v}(\theta)}$$

- $\mathbf{v}(\theta)$ encodes how the plane wave impinges for each θ
- Scan for different values of θ and Pick K largest peaks
- Insufficient data causes higher sidelobes in the scan angle (θ) space

- Parameter estimate $\hat{\theta}$ given by location of maximum power



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State-of-the-art array processing

- Since 1950's much progress in exploiting structure:
 - Unitary invariance
 - Centro-symmetry
 - Dynamics of the target being tracked
 - etc.
- Techniques refined and tested over years
- **Central role** of sample covariance matrices
 - New mathematics yet to be fully taken advantage of!

Opportunities for collaboration

- Large # sensors, small # samples common for decades!
 - 16-100 common in radar
 - 1000's in sonar
 - Systems being planned: 10,000's
- Modes of collaboration:
 - Probabilistic *analysis* of algorithms (lots of low-hanging fruit!)
 - *Statistical optimization* of existing algorithms
 - *Inspiring* new algorithms
- Extensive real-world data sets available for testing
 - e.g. Global warming studies in Arctic with large arrays (1980's)
- Array processing problems as test-bed for refining methodologies
 - Other applications (almost surely) will follow

Fundamental challenge/question

- Sample covariance matrices appear in many applications

- Hope that the “new” mathematics of random matrices inspire fundamentally new signal processing paradigms

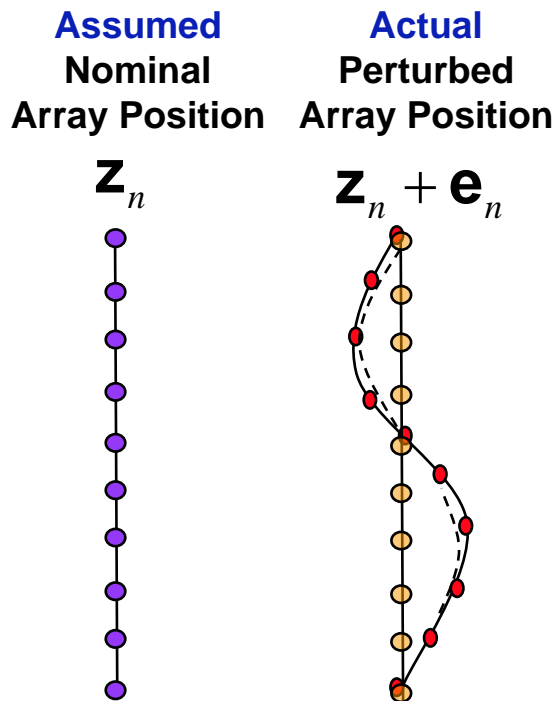
- **A word of caution:**

- Role of mismatch between assumed model and reality

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Role of model mismatch : Example



- Theory: Array is a straight line (“linear array”)
- In practice: Array elements wiggle a bit
 - (e.g. when being towed behind a ship)
- Over-zealous mathematical solutions:
 - Model the wiggling as well?
 - Fancy optimization over worst case wiggling?
- Real-world solution: “simple” modifications of simple algorithms work best!

- e.g.
$$\hat{P}_{\text{Capon}}(\theta) = \frac{1}{\mathbf{v}^H(\theta) \hat{\mathbf{R}}^{-1} \mathbf{v}(\theta)}$$

- Testing with data sets only way to know for sure
- Moral: Remain confident in mathematical solution but resist temptation to over-optimize!

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Mathematical Questions (abridged)

- Given true \mathbf{R} , subspace spanned by a set of eigenvectors is (often) sufficient to extract signals
- Large sensors, Small data situation:
 - Blurring of eigenvalues + Blurring of eigenvectors
- Much more known about eigenvalues than eigenvectors
 - Eigenvectors more important in practice (eigenvalues can always be tweaked!)

- Analysis: Blurring of eigenvectors
 - Models of interest:
 - Rectangular random matrices
 - Matrix valued processes
- Design:
 - Parametric deblurring of sample eigenvalues: Possible
 - Parametric deblurring of sample eigenvectors: Possible?
- Non-parametric approaches to combat model sensitivity: Possible?

Summary

- Lots of existing well-defined problems to get feet wet!
- New ideas from random matrix theory appear particularly relevant
- Mathematics fundamental enough to eventually be useful
- Collaborations accelerate the process