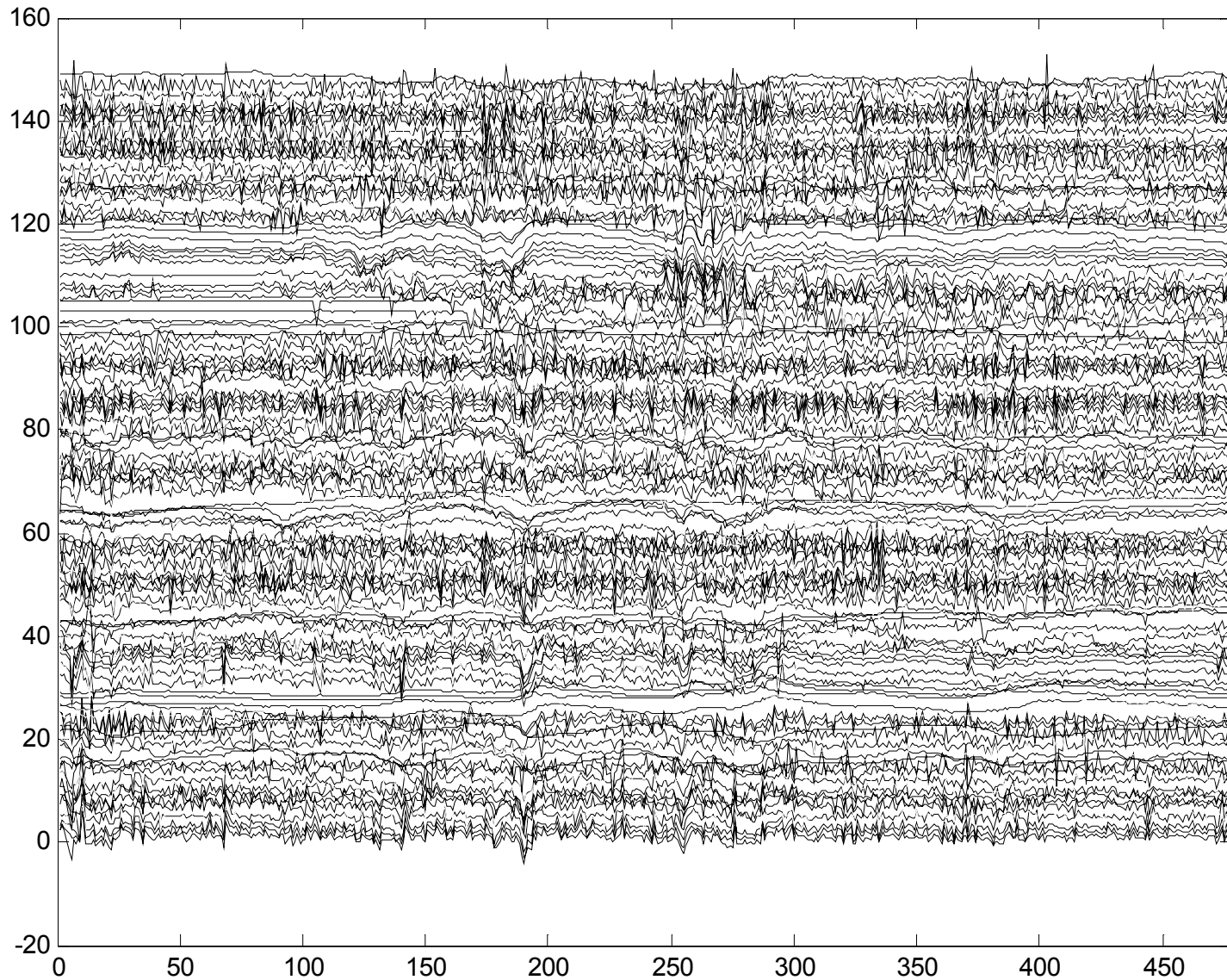


The principal components estimator of large factor models

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US macroeconomic data, 2-nd half of 20th century



Large factor models in economics

$$\underset{n \times T}{X} = \underset{n \times r}{L} \underset{r \times T}{F'} + \underset{n \times T}{e}$$

- Applications: arbitrage pricing theory, factor augmented VARs, diffusion index forecast models
- Factor domination idea:

$$\max eval\left(\frac{ee'}{T}\right) < u, \quad \min eval\left(L' L \frac{F' F}{T}\right) \rightarrow \infty$$

- PC estimator: $\hat{F} = \sqrt{T} evect(X' X / T), \quad \hat{L} = X \hat{F} / T$

My assumptions

Assumption 1: Factors are either deterministic or stationary,
 $E(F' F / T) = I$, $L' L$ is diagonal

Assumption 2: Idiosyncratic terms are i.i.d. $N(0, \sigma^2)$

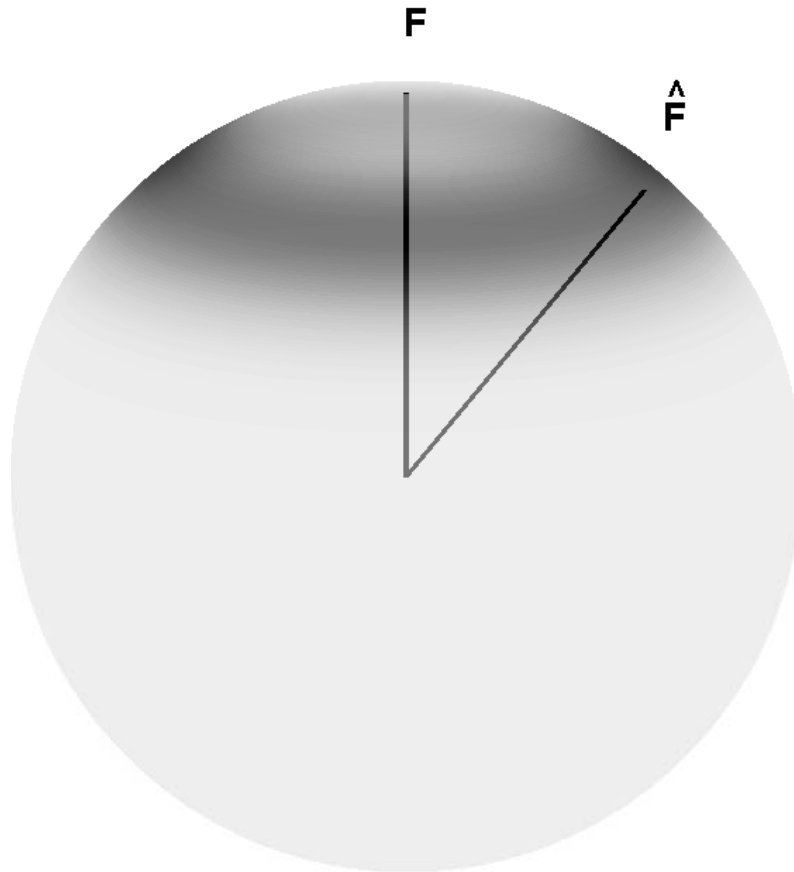
Assumption 3: $L' L = \text{diag}(d_1, \dots, d_k) + o(n^{-1/2})$,

$$n / T = c + o(n^{-1/2})$$

$$\sqrt{T}(F' F / T - I) \rightarrow \Phi$$

Theorem 1: $\hat{F} = F \cdot Q + F^\perp, \quad Q = Q^{(1)} + \frac{1}{\sqrt{T}} Q^{(2)},$

$Q^{(1)} < I, \quad Q^{(2)} \rightarrow N(0, \Omega)$



Workings of the PC estimator

Let $F = (\sqrt{T}, 0, 0, \dots, 0)'$ and $L = (\sqrt{d}, 0, 0, \dots, 0)'$

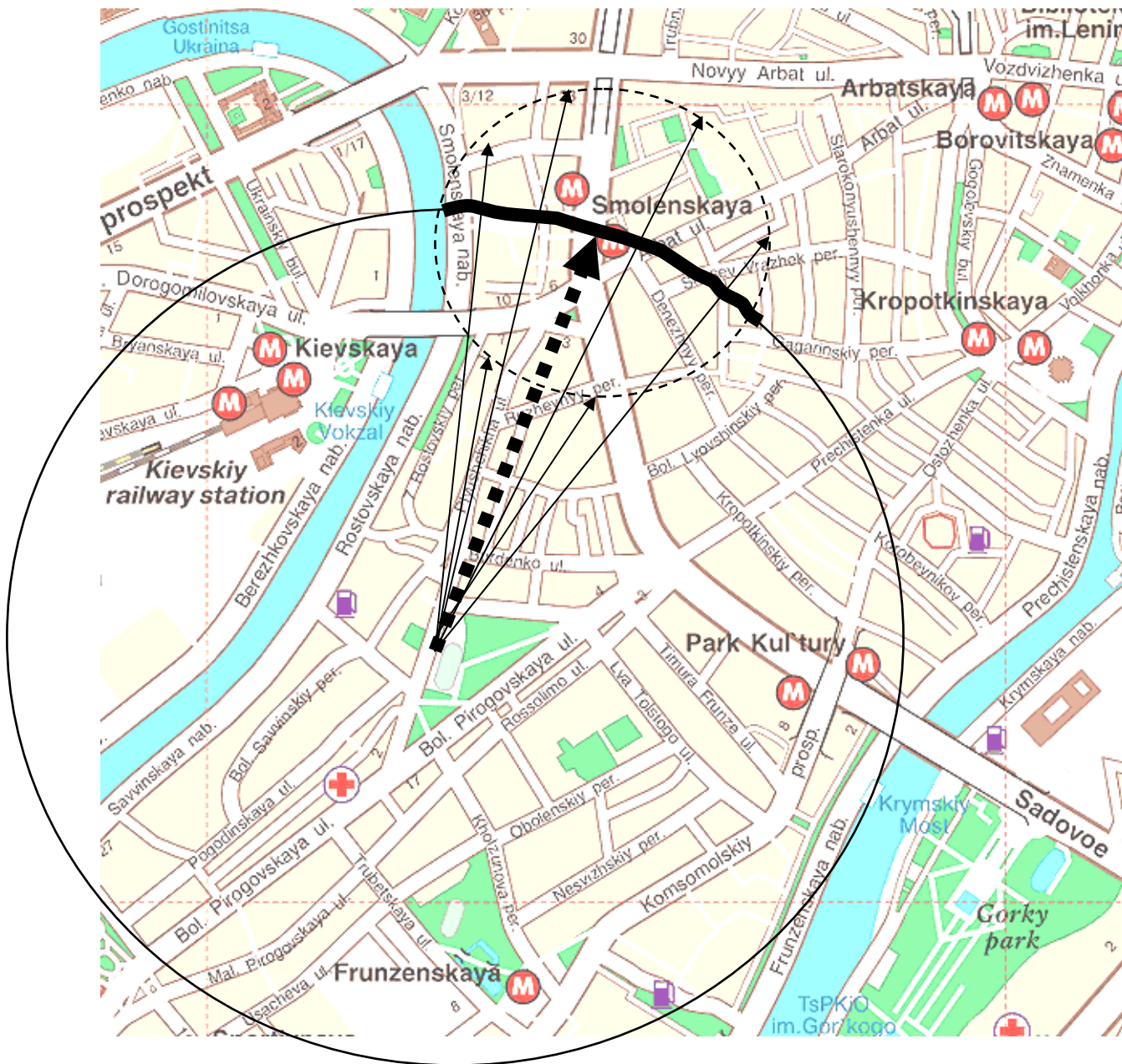
$$\text{Then } \frac{X'X}{T} = d \frac{(F + \varepsilon_1)(F + \varepsilon_1)'}{T} + \frac{\varepsilon_{-1}'\varepsilon_{-1}}{T}$$

The PC direction is u such that

$$d \cdot u' \frac{(F + \varepsilon_1)(F + \varepsilon_1)'}{T} u + u' \frac{\varepsilon_{-1}'\varepsilon_{-1}}{T} u \rightarrow \max$$

The first term is maximized when $u \uparrow\uparrow F + \varepsilon_1$

The second, when $u \uparrow\uparrow \max \text{evec} \left(\frac{\varepsilon_{-1}'\varepsilon_{-1}}{T} \right)$



Poincaré's observation

- A random direction in a high-dimensional space is nearly orthogonal to any fixed direction with high probability
- More precisely, let S^n be the Euclidean sphere with rotation-invariant measure μ . Fix x_0 on S^{n+1} . Then:

$$\mu\{x \in S^{n+1} : |x' x_0| > \varepsilon\} \leq \sqrt{\frac{\pi}{2}} \exp(-\varepsilon^2 n / 2)$$

The good, the bad, and the ugly

$$\sqrt{T}(\hat{L}_{ij} - \rho L_{ij}) \rightarrow N(0, \Gamma), \quad d_j > \sigma^2 \sqrt{c}$$

- $\Gamma = \frac{\sigma^2}{d_j}$

- $\Gamma = \sum_{\substack{s=1 \\ s \neq j}}^k L_{is}^2 \frac{(d_j + \sigma^2)(d_s + \sigma^2)}{(d_j - d_s)^2} + \left(1 - \sum_{s=1}^k L_{is}^2\right) \frac{\sigma^2(d_j + \sigma^2)}{d_j^2}$

- $\Gamma = \sum_{\substack{s=1 \\ s \neq j}}^k L_{is}^2 \frac{d_j(d_j + \sigma^2)(d_s + \sigma^2)}{(d_j + c\sigma^2)(d_j - d_s)^2} + \left(1 - \sum_{s=1}^k L_{is}^2\right) \frac{\sigma^2(d_j + \sigma^2)}{d_j(d_j + c\sigma^2)}$
 $+ L_{ij}^2 \frac{c\sigma^4 d_j (d_j + \sigma^2)^2}{(d_j + c\sigma^2)(d_j^2 - c\sigma^4)^2} \left(1 + c \left(\frac{d_j + \sigma^2}{d_j + c\sigma^2}\right)^2\right)$

Conclusion

- We find explicit formulae for the amount of inconsistency and the asymptotic distribution of the PC estimator of large spherical factor models
- More work is needed to generalize results to correlated idiosyncratic terms and to dynamic factor models