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A Generative Phonetic Analysis of the Timing of L- Phrase Accents in English

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The timing of L- phrase accents in English

• Pierrehumbert (1980) posits leftward spreading of L- in H*L-H% and H*L-L% tunes to explain why F0 does not interpolate from H* to the end of the phrase.



- Where does the low plateau associated with L-begin?
- Two hypotheses (Pierrehumbert 1980):

➤ L- occurs at a fixed interval after H*

 \succ L- is aligned to the end of the nuclear-accented word.

Generative phonetics

- Many details of phonetic realization are language-specific
- So the outputs of a grammar must be phonetic representations
 - What does the phonetic component of grammar look like?
- Pioneering work on this topic concerns the phonetics of intonation (Pierrehumbert 1980, Pierrehumbert & Beckman 1988)

- General scheme for implementation of tones (Pierrehumbert 1980):
 - Locate tone targets in time
 - > Assign F0 values to targets

> Interpolate between targets



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Propose a revised organization for phonetic grammar of tone:

- F0 production is modeled as the response of a dynamical system to a control signal (cf. Fujisaki & Hirose 1984)
 - Control signal consists of step functions connected by linear ramps
- Select the control signal that generates the F0 trajectory that best satisfies constraints on:
 - realization of tone targets
 - alignment of tone targets
 - articulatory constraints

H* L-L% 'eiliənən arə'lerrə-



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- Target assignment and interpolation are combined
- More explicit model of the interpolation function
- Mapping from tones to F0 trajectory is derived by optimization with respect to conflicting, violable constraints
 - cf. context sensitive realization rules
- The same approach is applicable to segmental realization, given an appropriate production model (cf. Flemming 2001).



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Identifying elbows

- To analyze the timing of L- we have to be able to locate it
 - The correlate of L- is an 'elbow' in the F0 trajectory
 - 'it was very difficult to decide where the L- was located.' (Pierrehumbert 1980:86)
- Many tones correspond to F0 elbows rather than F0 maxima or minima
 - e.g. rises and falls to/from F0 plateaus (L LH, HL L, LH H, etc) (Flemming & Cho 2017, D'Imperio 2000, Welby 2007 etc)
 - need to be able to locate these tonal targets in order to develop comprehensive models of tonal timing.



Identifying elbows

- Algorithms for locating F0 elbows have been proposed (e.g. del Giudice et al 2007, Reichel & Salveste 2015)
 - difficult to evaluate because there is no independent evidence concerning the true locations of elbows.
- The proper criterion for positing a target is that it accounts for the observed F0 contour.
- Analysis-by-synthesis using the model outlined above.
 - Assume:
 - > H* target corresponds to the F0 peak
 - Transitions from H to L take a particular form (explicit model of the interpolation function)
 - Infer the location of L- by fitting the transition model to the H*Ltrajectory.



- F0 falls are modeled as the response of a dynamical system to a step function input.
 - actually model log(F0)
- Transition from first L- target to the second is modeled as a linear transition.
- cf. Fujisaki & Hirose 1984, Anderson et al 1984



- The dynamical model is a cascade of 4 first-order linear dynamical systems (Birkholz et al 2011).
 - provides a good fit to the contours
 - small number of parameters:
 - F0 targets for H* and L-
 - time constant ('stiffness')
 - initial acceleration
 - slope of plateau



- Parameters for the H*L- falling transition:
 - F0 targets for H* and L-
 - time constant ('stiffness')
 - initial acceleration



- Parameters for the H*L- falling transition:
 - F0 targets for H* and L-
 - time constant ('stiffness')
 - initial acceleration



- The movement never quite reaches its target
 - The end of the transition is taken to be within 2% of the target
 - For a given initial acceleration, the trajectory scales in time with T_{12}



Models of F0 production

- Critically-damped second order ('spring-mass') systems are more familiar as models of F0 movements (Fujisaki & Hirose 1984) and articulator movements (Browman & Goldstein 1992).
- Damped second order system has peak acceleration at movement onset.
 - But this is not true of many F0 movements, resulting in poor fits for this kind of model



- This problem is familiar from the study of other speech movements (e.g. Kröger et al 1995)
- Cascaded First Order system can accommodate variation in acceleration profiles of movements.

Testing hypotheses about the timing of L-

• Pierrehumbert (1980) posits leftward spreading of L- in H*L-H% and H*L-L% tunes to explain why F0 does not interpolate from H* to the end of the phrase.



- Where does the low plateau associated with L-begin?
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➤ L- occurs at a fixed interval after H*

 \succ L- is aligned to the end of the nuclear-accented word.

Predictions of the two hypotheses

• How should the time from H* to L- elbow change when the interval between H* and the end of the word changes?



The Data

- Recordings from Barnes, Veilleux, Brugos & Shattuck-Hufnagel (2010)
- 25 two-word phrases in a context designed to elicit H* L- H% melody, with H* on the first word.
- First word: vary the number and length of syllables following primary stress
 - 2 álien, lánolin, Líllian, Márilyn, mínimum
 - 3 lúminary, pálimony, céremony, cúlinary, púlmonary
 - 3 críminally, sérially, términally, mínimally, nóminally
 - Experimenter: George is a thoughtful sort of divorce lawyer—I go to him whenever I need a palimony ruminator.
 Subject: A palimony ruminator???!!! (H* L-H%) I thought he was figuring out your plumbing problems!

The Data

- 15 speakers (11 female), each produced 4 repetitions of the materials.
- 242 utterances excluded due to errors, disfluencies, pitch tracking problems, leaving 1258 observations.
- Tracked F0 with Praat (Boersma & Weenink 2018),
- Segmented the pitch contour from F0 peak (H*) to onset of the final rise (if any).
- Fitted the tone realization model by minimizing summed squared errors.
 - Identified L- 'elbow' target based on the fitted model



Results





- Neither hypothesis is supported (cf. Barnes et al 2010)
 - Time from H* to L- elbow is not fixed it tends to increase as duration from H* to end of word increases ($\beta = 0.22, t = 5.5$)
 - But L- elbow does not track word end (dashed line)
- Substantial variation between and within (most) subjects

Analysis

- Timing of L- elbow is a result of compromise between two conflicting constraints :
 - \succ L- should start at a fixed interval D after H*
 - preferred duration for an HL fall (cf. Cho 2010)
 - ➤ L- should start well before the end of the accented word
 - to keep H*L- distinct from tunes with a pitch accent on a following word (H* !H*, H* L*) (cf. Barnes et al 2010)
- These constraints conflict if the preferred fall duration would place Ltoo close to the end of the word
 - The conflict is resolved by compromise (cf. Flemming 2001).



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Analysis

- Time of $H^* = 0$, *L* is the time of the initial target for L-
 - \succ L- should start at a fixed interval D after H*

L = D penalty for violation: $(L-D)^2$

 \blacktriangleright L- should start at least *m* seconds before the end of the accented word, *e*

L < e-m penalty for violation: $(L-(e-m))^2$



- Select *L* to minimize the weighted sum of constraint violations: $w_D(L-D)^2 + w_e(L-(e-m))^2$
- Optimal value of *L* is a weighted average of *D* and *e*-*m*

$$L = \frac{w_D D + w_e(e - m)}{w_D + w_e}$$

- if w_e is much lower than w_D , then the effect of word boundary is weak.

Analysis

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L < e-m penalty for violation: $(L-(e-m))^2$



• Optimal value of L is a weighted average of D and e-m

$$L = \frac{w_D D + w_e(e - m)}{w_D + w_e}$$

- The observed relationship between L and time to word boundary is derived if $w_D = 1$, $w_e = 0.28$, D = 0.25s, m = 0.19s
 - *D* and *m* are not uniquely identifiable, but these values are compatible with the data.

Variation between speakers

• Relationships between duration from H* peak to L- elbow and duration from H* peak to end of word, plotted by subject



- Substantial variation in intercepts, and some variation in slope.
- Variation in intercept can be derived from variation in *D*
 - Suggests that *D* may be derived from compromise between effort minimization (high T) and a preference for a steep fall from H to L.
 - D variation then results from variation in constraint weights.
- Variation in slope follows from variation in ratio of w_D to w_e

Summary

- Study of timing of L- phrase accents in English motivates a model of tonal realization in which:
- F0 trajectories are modelled as the response of a dynamical system to a control signal that consists of a sequence of step functions connected by linear ramps.
 - Specifying the mechanism that generates F0 trajectories allows for identification of F0 targets, including elbows. through analysis-by-synthesis.
- The mapping from tones to F0 trajectory is derived by optimization with respect to conflicting constraints
 - The timing of L- is a compromise between a preferred duration for H*L- falls, and a weak preference to reach L- before the end of the accented word.
- The same structure should be applicable to the grammar of segmental phonetics (cf. Flemming 2001).

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