# Macroscopic traffic models 

Traffic Flow Theory
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1.041/1.200 Transportation: Foundations and Methods

## Readings

1. C. Daganzo, Fundamentals of transportation and traffic operations, vol. 30. Pergamon Oxford, 1997. Chapter 4: Traffic flow theory. URL.

## Outline

1. Basic assumptions of traffic flow theory
2. Fundamental diagrams (FDs)
3. Highway delay problem

## Unit 1: Traffic flow fundamentals



## Outline

1. Basic assumptions of traffic flow theory
a. Key variables
b. Time vs space means
2. Fundamental diagrams (FDs)
3. Highway delay problem

## Traffic flow theory

- Today: From traffic flow (traffic streams) to traffic flow theory
- Traffic flow theory:
- Models and hypotheses for explaining traffic flow
- I.e., what would happen to traffic streams if they were to flow on roads under different conditions, potentially not yet observed
- Models vs data




## Basic assumptions

1. Study of a single traffic stream, flowing on a facility with a single entrance and a single exit
2. Uninterrupted traffic

- Traffic regulated by interactions between vehicles, as opposed to being regulated by external means
- E.g. on a highway or at unsignalized intersections, as opposed to traffic lights, stop signs.

3. Stationary traffic conditions (vs. time and space-varying dynamics)

## Stationary vs non-stationary traffic

## Stationary traffic conditions

(vs. time- or space-varying dynamics):

- Traffic is stationary if it is a superposition of families of trajectories that are each parallel and equidistant.

(a)

(b)

(c)

Examples of non-stationary traffic

## Traffic stream variables

- Main variables
- Flow
- Time headway
- Density
- Spacing
- Speed (space-mean, time-mean)

" Aim: Obtain relationships that hold "on average"; i.e. for large stationary time-space regions containing many vehicles


## Formulas for traffic characteristics

Table 4.1.. Generalized formulas for various traffic characteristics using two observation methods. Boxed expressions correspond to the original definitions introduced in Chapter 1:

|  | Method of Observation |  |
| :---: | :---: | :---: |
|  | Instantaneous photograph at time $t_{0}$ (section length, $\mathbf{L}$ ) | Observation from a fixed location $x_{0}$ (duration, T ) |
| Density, $k$ (A) | $n / L$ | $\frac{1}{T} \sum_{j=1}^{m} \mathrm{p}_{\mathrm{j}}=\frac{1}{T} \sum_{j=1}^{m} \frac{1}{u_{j}}$ |
| Flow, $\mathrm{q}(\mathrm{A})$ | $\frac{1}{L} \sum_{i=1}^{n} v_{i}$ | m/T |
| Space-mean speed, $\mathrm{v}(\mathrm{A})$ | $\frac{1}{n} \sum_{i=1}^{n} v_{i}$ | $\left[\frac{1}{m} \sum_{j=1}^{m} p_{j}\right]^{-1}=\left[\frac{1}{m} \sum_{j=1}^{m} \frac{1}{u_{j}}\right]^{-1}$ |
| Average pace, $\mathrm{p}(\mathbf{A})$ | $\left[\frac{1}{n} \sum_{i=1}^{n} v_{i}\right]^{-1}$ | $\frac{1}{m} \sum_{j=1}^{m} p_{j}$ |
| t(A) | ndt | $d x \sum_{j=1}^{m} p_{j}$ |
| $\mathrm{d}(\mathbf{A})$ | $d t \sum_{i=1}^{n} v_{i}$ | mdx |

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## Time and space means

- Space-mean: averages taken at an instant over a space interval
- Time-mean: averages taken at a specific locatio (with time-varying over an interval)
- Speed:
- $\bar{v}_{s}$ : space-mean speed
- $\overline{v_{t}}$ : time-mean speed

- Other vehicle characteristics can be averaged across space or time. E.g., occupancies (number of persons per vehicle), energy consumption, emissions, etc.
- There is no a priori reason to expect averages taken across space or time to be the same.
- Example: You own two cars, they are both driven an equal distance of 100 miles. One gets 20 miles per gallon $(\mathrm{mpg})$, the other 50 mpg . Is the average mpg 35 (i.e. $\frac{50+20}{2}$ )?


## Time and space means

Table 4.1. Generalized formulas for various traffic characteristics using two observation methods. Boxed expressions correspond to the original definitions introduced in Chapter 1:

## Method of Observation

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| :--- |
| from a fixed location $x_{0}$ |
| (duration, T) |



- Notation:
- $v_{i}=$ velocity ( $\mathrm{mi} / \mathrm{hr}$ ) of vehicle $i$
- $p_{j}=$ pace ( $\mathrm{hr} / \mathrm{mi}$ ) of vehicle $j$
- $u_{\mathrm{j}}=$ velocity (mi/hr) of vehicle $j, \mathrm{u}_{\mathrm{j}}=\frac{1}{p_{j}}$
- If traffic is stationary, then time-
mean speed = space-mean speed.
- Proof: $v=v_{i}=\frac{1}{p_{j}}, \forall i, j$


## Time and space means in practice

- Time-mean speeds: Often how dual inductance loop detectors in traffic management systems are configured
- Ex. arithmetic average of vehicle speeds over 20 -second intervals
- Space-mean speeds: In nearly all cases of traffic analysis, space-mean speeds should be used
- Statistically more stable in short segments/durations
- Weighs slower vehicles' speeds more heavily

Space-mean speed $v(\boldsymbol{A}) \equiv v_{S}(\boldsymbol{A})$
mean over space interval (specific time)


Figure 1.4 Time-space trajectories of two vehicle families.
Time-mean speed $v_{t}(\boldsymbol{A})$
mean over time duration (specific location)

## Time and space means in practice

- In practice, timemean and spacemean speeds differ by 1-5\%
- Differences are greater when there is more variability in speed (more congestion)

Table 1-1. Comparison of Time-Mean and Space-Mean Speeds

| Data Items | Run 1 | Run 2 | Run 3 | Run 4 | Run 5 | Sum | Average | Variance |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Travel Time (sec) | 153 | 103 | 166 | 137 | 127 | 686 | 137.2 |  |
| Running Time (sec) | 142 | 103 | 141 | 137 | 127 | 650 | 130.0 |  |
| Stopped Delay Time <br> (sec) | 11 | 0 | 25 | 0 | 0 | 36 | 7.2 |  |
| Average Travel Speed <br> (km/h) | 44.7 | 66.4 | 41.2 | 49.9 | 53.9 | 256 | 51.2 | 95 |
| Average Running <br> Speed $(\mathrm{km} / \mathrm{h})$ | 48.1 | 66.4 | 48.4 | 49.9 | 53.9 | n.a. | 52.6 |  |
| Section Length $=1.9 \mathrm{~km}$ |  |  |  |  |  |  |  |  |
| Difference between Time-Mean Speed and Space-Mean Speed <br> Time-Mean Speed $=\sum($ speeds $) /$ no. of runs $=256 / 5=51.2 \mathrm{~km} / \mathrm{h}$ <br> Space-Mean Speed $=$ no. of runs $\times$ distance $/ \sum($ travel times $)=5 \times 1.9 / 686=49.8 \mathrm{~km} / \mathrm{h}$ <br> Therefore, difference $=1.4 \mathrm{~km} / \mathrm{h}$ |  |  |  |  |  |  |  |  |
| Check Equation 1-5: Time-Mean Speed $\approx 49.8+95 / 49.8 \approx 51.7 \mathrm{~km} / \mathrm{h} \approx 51.2 \mathrm{~km} / \mathrm{h}$ |  |  |  |  |  |  |  |  |

## Outline

1. Basic assumptions of traffic flow theory
2. Fundamental diagrams (FDs)
a. Basic relationship
b. FDs versus time-space diagrams
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## Basic relationship of traffic flow

$$
q=v_{s} k
$$

where:

- $q$ : flow [veh/h]
- $v_{s}$ : speed (space-mean speed) [mi/h] or [km/h]
- $k$ : density [veh/mi] or [veh/km]
- These are the three fundamental variables of traffic flow.


## Traffic stream models

(1) Speed-density model

- Greenshields (1935), seminal work, assumes a linear relationship between speed and density
- From experimental data:
- Light traffic $\rightarrow$ high speed
- Heavy traffic $\rightarrow$ low speed (near zero).
- $v_{f}$ : free flow speed
- $k_{\text {cap }}=k_{j}$ : jam density



## Traffic stream models





## Traffic stream models are interrelated

(1) Speed-density model

- Greenshields (1935), seminal work, assumes a linear relationship between speed and density
- $v_{f}$ : free flow speed
- $k_{\text {cap }}=k_{j}$ : jam density
- What is the corresponding relationship between flow and density?



## Interpretation of traffic stream models

- Each diagram relates the three fundamental variables, and are therefore called fundamental diagrams.
- For a given road, a fundamental diagram is fitted based on measurements
- Points on the diagram describe possible traffic conditions
- These relationships are postulated to be true "on average"



## Fundamental Diagram in practice

- Paris: boulevard periphérique
- Three locations (detectors)
- Measurements of car passages (traffic counts) and occupancies for each detector over a chosen time interval
- Source: Papageorgiou et al. (1990) Modelling and real-time control of traffic flow on the southern part of Boulevard Peripherique in Paris: Part I: Modelling, Transportation Research: Part A



## Fundamental Diagram in practice

- Flow-density model
- Measurements of car passages (traffic counts) and occupancies for each detector over time interval: 6am-10am of Nov. 271987
- Flow-density (volume-occupancy) diagrams taken over one-minuteintervals for a given location
- Traffic Occupancy (in \%) (Def.: \% of loop occupancy in a given time period)
- Conditions: heavily congested traffic after 7:40am, rainy





## Triangle model

(3) Flow-density model


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Fundamental diagram $+(\mathrm{t}, \mathrm{x})$-diagram



Source: C. Daganzo (1997)

## Recall: traffic waves



Vehicle trajectories (Sugiyama et al. 2008)


## Traffic waves: fundamental diagram characterization



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## Highway delay problem

A freeway exhibits a triangular flow-density relation with parameters: $v_{f}$ (free flow speed), $q_{\max }$ (capacity) and $k_{j}$ (jam density)

1. Plot the fundamental diagram and derive an expression for the function that gives the (space-mean) speed as a function of density inside a queue.

- Don't forget to specify the range of $k$ for which the equation holds.

2. If $k_{j}=600 \mathrm{veh} / \mathrm{mile}, v_{f}=1 \mathrm{mile} / \mathrm{min}$ and $q_{\max }=100 \mathrm{veh} / \mathrm{min}$. Determine the delay experienced by a vehicle that joins a 2 mile queue caused by a bottleneck that flows at $q=50$ veh $/ \mathrm{min}$.

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## References

1. C. Daganzo, Fundamentals of transportation and traffic operations, vol. 30. Pergamon Oxford, 1997. Chapter 4: Traffic flow theory
2. Prof. Nikolas Geroliminis' lecture Fundamentals of Traffic Operations and Control, Spring 2010 EPFL
3. Lecture notes: Principles of Highway Engineering and Traffic Analysis (2009) by Fred Mannering, Scott Washburn and Walter Kilareski
4. Lecture notes: 9th Dynamic Traffic Flow Modeling and Control (2010) by Prof. Markos Papageorgiou
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6. Many slides adapted from Carolina Osorio
