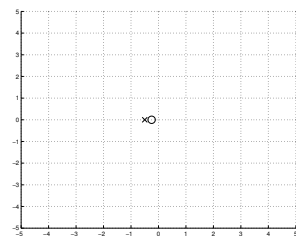
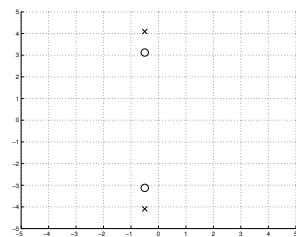
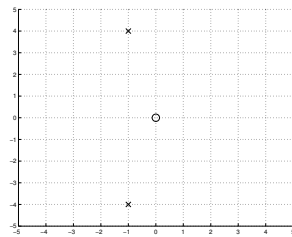
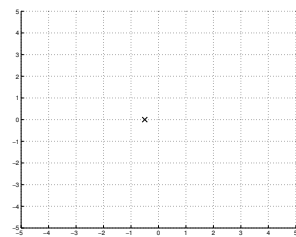
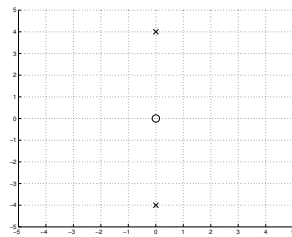
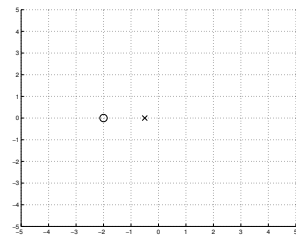
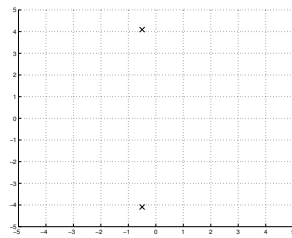
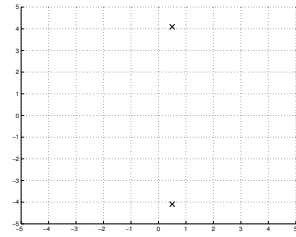
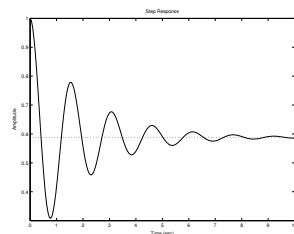
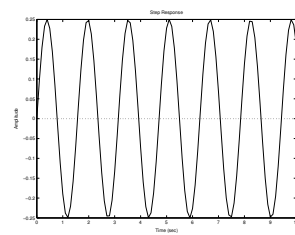
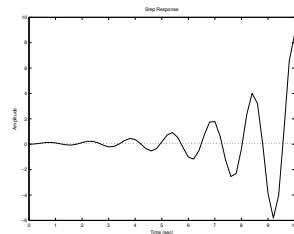
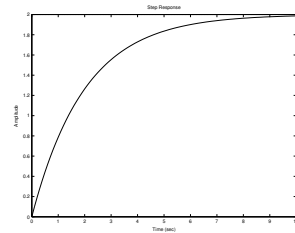
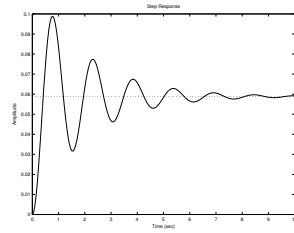
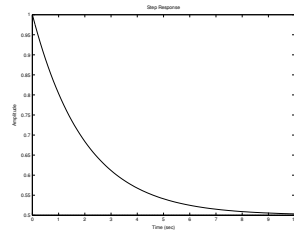
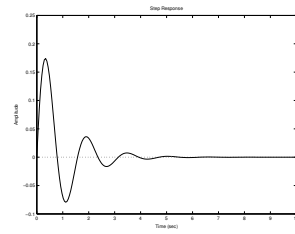
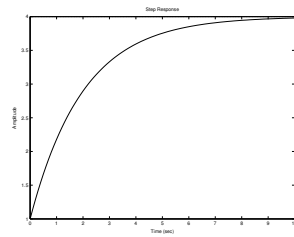
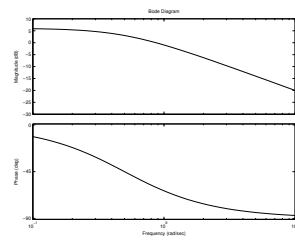
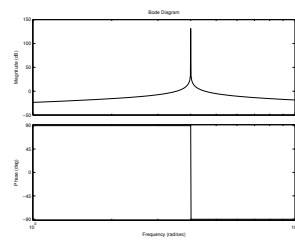
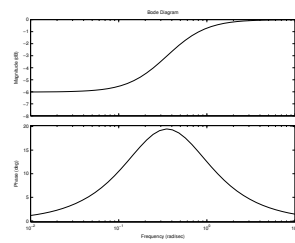
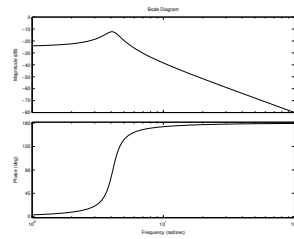
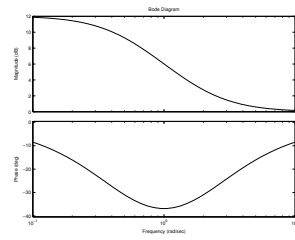
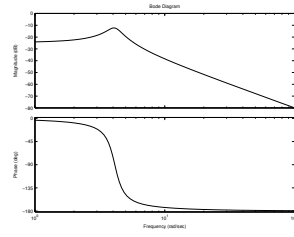
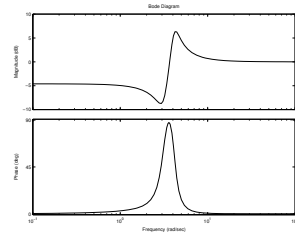
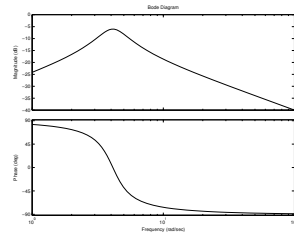


Problem 1

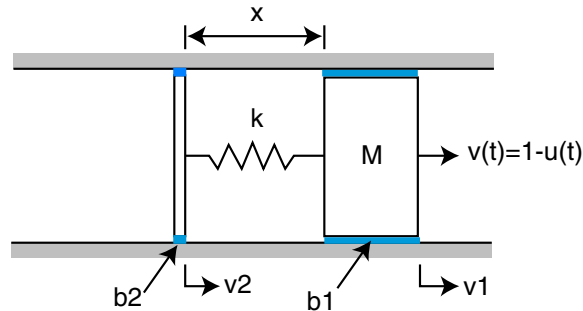
Match each of the following pole-zero diagrams to the corresponding Bode plot and step response from the following two pages. For example if you think that pole-zero diagram (1) corresponds to step response (q) and Bode plot (r), write "1,q,r" on your exam paper.







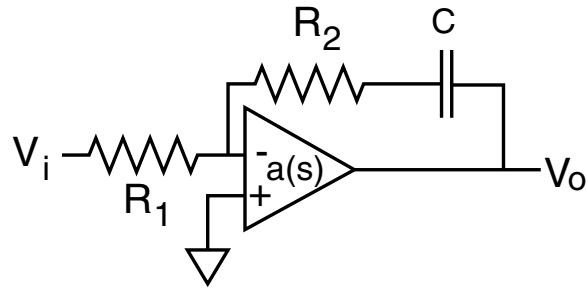
Problem 2



The figure above shows a system which consist of a mass (M), spring (k), and two dampers (b_1 , b_2). The spring is attached at one end to the mass and to the damper (b_2), which is massless at the other. The mass is pulled by a velocity source ($v(t)$). x denotes the extension of the spring. v_1 is the velocity of the mass and v_2 is the velocity of the second damper. $M = 1$ kg, $b_1 = 1$ Ns/m, $b_2 = 9$ Ns/m, $k = 9$ N/m.

- find $v_1(0^-)$, $v_2(0^-)$, and $x(0^-)$
- find $x(0^+)$ and $\dot{x}(0^+)$
- write the differential equation for the system in terms of x .
- find $x(t)$ given the initial conditions in c.

Problem 3



- a) If $a(s) = 10^6$, find the transfer function of Op-Amp circuit above.
- b) If this circuit were used as a controller, what type of controller would it be?
- c) If $a(s) = \frac{10^6}{s}$ what is the transfer function of the circuit?
- d) $C = 1 \mu F$, $R_1 = 1e4 \Omega$, $R_2 = 5e4 \Omega$. Plot $M(\omega)$ and $\phi(\omega)$