6.033 - Operating Systems: Performance
Lecture 7
Katrina LaCurts, lacurts@mit.edu

# 0. Previously

- Enforced modularity on a single machine via virtualizationVirtual memory, bounded buffers, threads
- Saw monolithic vs. microkernels
- Talked about VMs as a means to run multiple instances of an OS on a single machine with enforced modularity (bug in one OS won't crash the others)
  - Big thing to solve was how to implement the VMM. Solution: trap and emulate. How the emulation works depends on the situation.
    - Another key problem: how to trap instructions that don't generate interrupts.

# 1. What's left? Performance

- Performance requirements significantly influence a system's design
- Today: general techniques for improving performance

# 2. Technique 1: buy new hardware

- Why? Moore's law => processing power doubles every 1.5 years, DRAM density increase over time, disk price (per GB) decreases,
- But:
  - Not all aspects improve at the same pace
  - Moore's Law is plateauing
  - Hardware improvements don't always keep pace with load increases
- Conclusion: need to design for performance, potentially re-design as load increases

# 3. General approach

- Measure the system and find the bottleneck (the portion that limits performance)
- Relax (improve) the bottleneck

#### 4. Measurement

- To measure, need metrics:
  - Throughput: number of requests over a unit of time
  - Latency: amount of time for a single request
  - Relationship between these changes depending on the context
  - As system becomes heavily-loaded:
    - Latency and throughput start low. Throughput increases as users enter, latency stays flat...
    - ..until system is at maximum throughput. Then throughput plateaus, latency increases
  - For heavily-loaded systems: focus on improving throughput
- Need to compare measured throughput to possible throughput: utilization
- Utilization sometimes makes bottleneck obvious (CPU is 100%

- utilized vs. disk is 20% utilized), sometimes not (CPU and disk are 50% utilized, and at alternating times)
- Helpful to have a model in place: what do we expect from each component?
- When bottleneck is not obvious, use measurements to locate candidates for bottlenecks, fix them, see what happens (iterate)
- 4. How to relax the bottleneck
  - Better algorithms, etc. These are application-specific. 6.033 focuses on generally-applicable techniques
  - Batching, caching, concurrency, scheduling
  - Examples of these techniques follow. The examples related to operating systems (that's what you know), but techniques apply to all systems
- 5. Disk throughput
  - (HDDs, not SDDs -- those are coming later)
  - How does a disk work?
    - Several platters on a rotating axle
    - Platters have circular tracks on either side, divided into sectors.
      - Cylinder: group of aligned tracks
    - Disk arm has one head for each surface, all move together
    - Each disk head reads/writes sectors as they rotate past. Size of a sector = unit of read/write operation (typically 512B)
    - To read/write:
      - Seek arm to desired track
      - Wait for platter to rotate the desired sector under the head
      - Read/write as the platter rotates
  - How long does R/W take?
    - Example disk specs:
      - Capacity: 400GB
      - # platters: 5
      - # heads: 10
      - # sectors per track: 567-1170 (inner to outer)
      - # bytes per sector: 512
      - Rotational speed: 7200 RPM => 8.3ms per revolution
    - Seek time: Avg read seek 8.2ms, avg write seek 9.2ms
      - Given as part of disk specs
    - Rotation time: 0-8.3ms
      - Platters only rotate in one direction
    - R/W as platter rotates: 35-62MB/sec
      - Also given in disk specs
    - So reading random 4KB block:  $8.2ms + 4.1ms + \sim .1ms = 12.4$
    - -4096 B / 12.4 ms = 322KB/s
    - => 99% of the time is spent moving the disk
  - Can we do better?
    - Use flash? We'll get to that
    - Batch individual transfers?
      - .8ms to seek to next track + 8.3ms to read entire track =

- 9.1ms
- .8ms is single-track seek time for our disk (again, from specs)
- 1 track contains ~1000sectors \* 512B = 512KB
- throughput: 512KB/9.1ms = 55MB/s
- Lesson: avoid random access. Try to do long sequential reads.
  - But how?
    - If your system reads/writes entire big files, lay them out contiguously on disk. Hard to achieve in practice!
    - If your system reads lots of small pieces of data, group them

# Caching

- Already saw in DNS. Common performance-enhancement for systems
- How do we measure how well it works?
  - Average access time: hit\_time \* hit\_rate + miss\_time \* miss\_rate
- Want high hit rate. How do we know what to put in the cache?
  - Can't keep everything
  - So really: how do we know what to \*evict\* from the cache?
- Popular eviction policy: least-recently used
  - Evict data that was used the least recently
  - Works well for popular data
- Bad for sequential access (think: sequentially accessing a dataset
  - that is larger than the cache)
  - Caching is good when
    - All data fits in the cache
    - There is locality, temporal or spatial
  - Caching is bad for
    - Writes (writes have to go to cache and disk; cache needs to be consistent, but disk is non-volatile)
  - Moral: to build a good cache, need to understand access patterns
    - Like disk performance: to relax disk as bottleneck, needed to understand details of how it works

### 7. Concurrency/scheduling

- Suppose server alternates between CPU and disk:

Apply concurrency, can get:

- This is a scheduling problem: different orders of execution can lead to different performance
- Example:
  - 5 concurrent threads issue concurrent reads to sectors 71, 10, 92, 45, and 29.
  - Naive algorithm: seek to each sector in turn
  - Better algorithm: sort by track and perform reads in order.
     Gets even higher throughput as load increases
    - Drawback: it's unfair

 No one right answer to scheduling. Tradeoff between performance and fairness.

# 8. Parallelism

- Goal: have multiple disks, want to access them in parallel
- Problem: how do we divide data across the disks?
- Depends on bottleneck
  - Case 1: many requests for many small files. Limited by disk seeks. Put each file on a single disk, and allow multiple disks to seek multiple records in parallel
  - Case 2: few large reads. Limited by sequential throughput.
     Stripe files across disks.
- Another case: parallelism across many computers
  - Problem: how do we deal with machine failures?
  - (One) Solution: go to recitation tomorrow!

# 9. Alternative Technologies

- Talked a lot about HDDs. Why not use solid-state disks (SSDs)?
  - SSD: (typically) flash memory that exports a disk interface
- Flash memory = no moving parts
- Is it better? Some specs:
  - Sequential read: 400 MB/sec.
  - Sequential write: 200-300 MB/sec.
  - Random 4K reads: 5700/sec (23MB/s)
  - Random 4K writes: 2200/sec (9MB/s)
- Conclusions:
  - Sequential access still much faster than random access.
  - Write performance is noticeably worse
    - Flash can only erase large units at a time. writing a small block = read large block, modify it, write it back
    - Modern SSDs have complex controllers that try to optimize this
- SSDs are also more expensive
- Many performance issues are the same
  - HDDs and SSDs are slower than RAM
  - Can still avoid small writes with batching
- Lesson: even as technology improves, our performance techniques still apply. Understanding the details of your system (e.g., how the storage media works) is crucial.

### 10. Summary

- We can't magically apply any of the previous techniques. Have to understand what goes on underneath.
  - Batching: how disk access works
  - Caching: what is the access pattern
  - Scheduling/concurrency: how disk access works, how system is being used (the workload)
  - Parallelism: what is the workload
- 11. Useful numbers for your day-to-day-lives:
  - Latency:

- 0.00000001ms: instruction time (1 ns)
- 0.0001ms: DRAM load (100 ns)
- 0.1ms: LAN network
- 10ms: random disk I/O
- 25-50ms: Internet east -> west coast
- Throughput:
  - 10,000 MB/s: DRAM
  - 1,000 MB/s: LAN (or100 MB/s)
  - 100 MB/s: sequential disk (or 500 MB/s)
  - 1 MB/s: random disk I/O