6.1800 Spring 2024 **Lecture #5: Threads** understanding the "most mysterious code" in an OS



Examining Emoji Color Spaces:

Author: Jennifer Daniel on behalf of the Unicode Emoji Subcommittee To: Unicode Technical Committee Date: November 15, 2020 Last Updated: April 11, 2021



A Strategy for Improving the Coverage of Heart Emoji

Background

Hearts are among the most frequently used emoji. Users of emoji often juxtapose the existing nine colored-heart emoji next to each other to denote markers of emotion, identity or affiliation that are not represented with atomic emoji in the Unicode Standard (ex. Support of Belarus: 🤍 🤎 🤍, Bisexuality: 💖 💙 💜 , etc.).¹ It has also recently come to our attention that colored hearts are the most common emoji used in non-messaging spaces like Twitter bios.

Identifying emoji additions that have multiple-uses is increasingly important as emoji gain in popularity. The more emoji can operate as building blocks instead of specific images the more versatile, fluid, and useful they become.



how do we decide what features to add to a system?

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can we correctly predict how features will be used? who/what they'll impact?

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how do we decide what features to add to a system?

can we correctly predict how features will be used? who/what they'll impact?

who gets to make these decisions?

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Background



operating systems enforce modularity on a single machine using virtualization in order to enforce modularity + have an effective operating system, a few things need to happen

•••••

- 1. programs shouldn't be able to refer to (and corrupt) each others' **memory**
- 2. programs should be able to **communicate** with each other
- 3. programs should be able to share a **CPU** without one program halting the progress of the others

virtual memory



bounded buffers

(virtualize communication links)



assume one program per CPU (for today)



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today's goal: implement threads, which allow multiple programs to share a CPU

virtual memory -----

bounded buffers

(virtualize communication links)

threads (virtualize processors)





a thread is a virtual processor





```
// send a message by placing it in bb
send(bb, message):
 acquire(bb.lock)
 // spin until it's safe to send
  while bb.in - bb.out >= N:
      release(bb.lock)
      acquire(bb.lock)
  bb.buf[bb.in mod N] <- message</pre>
  bb.in <- bb.in + 1
  release(bb.lock)
  return
```



```
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 bb.buf[bb.in mod N] <- message</pre>
  bb.in <- bb.in + 1
  release(bb.lock)
  return
```

question: what are we hoping will happen in between release(bb.lock) and acquire(bb.lock)?



```
// send a message by placing it in bb
send(bb, message):
  acquire(bb.lock)
  // spin until it's safe to send
  while bb.in - bb.out >= N:
      release(bb.lock)
      yield()
      acquire(bb.lock)
  bb.buf[bb.in mod N] <- message</pre>
  bb.in <- bb.in + 1
  release(bb.lock)
  return
```



```
// send a message by placing it in bb
send(bb, message):
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      yield()
      acquire(bb.lock)
 bb.buf[bb.in mod N] <- message</pre>
  bb.in <- bb.in + 1
  release(bb.lock)
  return
```

yield()'s job is to suspend the current thread and resume another* thread; our first job today is to understand what that means

*there are cases where yield() might suspend the current thread and end up resuming the same thread; that's okay



yield():

// Suspend the running thread

// Choose a new thread to run

// Resume the new thread



t_lock makes yield() an atomic action

yield(): acquire(t_lock)

> // Suspend the running thread // Choose a new thread to run // Resume the new thread



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threads is a table that contains information about each of the current threads

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threads is a table that contains information about each of the current threads

for each thread it stores the thread's - state: RUNNABLE, RUNNING

yield() suspends the running thread, chooses a new thread to run, and resumes the new thread

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- state: RUNNABLE, RUNNING
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```
SP = current stack pointer
PTR = current page table register
```

```
yield():
  acquire(t_lock)
```

// Suspend the running thread id = id of current thread threads[id].state = RUNNABLE threads[id].sp = SP threads[id].ptr = PTR

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threads is a table that contains information about each of the current threads

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cpus is a table that keeps track of the id of the thread currently running on each cpu

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SP = current stack pointer
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yield():
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// Suspend the running thread id = cpus[CPU].thread threads[id].state = RUNNABLE threads[id].sp = SP threads[id].ptr = PTR

// Choose a new thread to run do: $id = (id + 1) \mod N$ while threads[id].state != RUNNABLE

// Resume the new thread



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yield() suspends the running thread, chooses a new thread to run, and resumes the new thread

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yield():
  acquire(t_lock)
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// Suspend the running thread
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threads[id].sp = SP
threads[id].ptr = PTR
```

```
// Choose a new thread to run
do:
```

```
// Resume the new thread
SP = threads[id].sp
PTR = threads[id].ptr
threads[id].state = RUNNING
cpus[CPU].thread = id
```

```
release(t_lock)
```



// send a message by placing it in bb send(bb, message): acquire(bb.lock) while **bb**.in - **bb**.out >= N: release(bb.lock) yield() acquire(bb.lock) bb.buf[bb.in mod N] <- message</pre> **bb.**in <- **bb.**in + 1 release(bb.lock) return

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performance concern: if the processor resumes the sending thread before any thread has called **receive()**, the buffer will still be full, and the sending thread will resume, but immediately yield again

yield() suspends the running thread, chooses a new thread to run, and resumes the new thread

```
yield():
  acquire(t_lock)
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thread until there's room in the buffer"

yield() suspends the running thread, chooses a new thread to run, and resumes the new thread

it would be nice if send() could indicate "yield, and don't resume this



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// send a message by placing it in bb send(bb, message): acquire(bb.lock) while **bb**.in - **bb**.out >= N: release(bb.lock) wait(bb.has_space) acquire(bb.lock) bb.buf[bb.in mod N] <- message</pre> **bb.**in <- **bb.**in + 1 release(bb.lock) notify(bb.has_message) return

```
new variables in use
```

bb.has_space = indicates that the buffer is not full (and so has space for at least one message) bb.has_message = indicates that the buffer has at least one message in it Katrina LaCurts | lacurts@mit.edu | 6.1800 2024



// send a message by placing it in bb send(bb, message): acquire(bb.lock) while **bb**.in - **bb**.out >= N: release(bb.lock) wait(bb.has_space) acquire(bb.lock) bb.buf[bb.in mod N] <- message</pre> **bb.**in <- **bb.**in + 1 release(bb.lock) notify(bb.has_message) return

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```
// receive a message from bb
receive(bb):
  acquire(bb.lock)
  while bb.out >= bb.in:
      release(bb.lock)
      wait( ? )
      acquire(bb.lock)
  message <- bb.buf[bb.out mod N]</pre>
  bb.out <- bb.out + 1
  release(bb.lock)
  notify( ? )
  return message
```



//	send a message by placing it in bb
1:	<pre>send(bb, message):</pre>
2:	acquire(<mark>bb</mark> .lock)
3:	while bb.in - bb.out >= N:
4:	<pre>release(bb.lock)</pre>
5:	<pre>wait(bb.has_space)</pre>
6:	acquire(bb.lock)
7:	<pre>bb.buf[bb.in mod N] <- message</pre>
8:	bb.in <- bb.in + 1
9:	<pre>release(bb.lock)</pre>
10:	<pre>notify(bb.has_message)</pre>
11:	return

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8:	bb.in <- bb.in + 1
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question: what happens if send() is interrupted between lines 4 and 5?

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problem: lost notify



```
// send a message by placing it in bb
send(bb, message):
  acquire(bb.lock)
 while bb.in - bb.out >= N:
      wait(bb.has_space, bb.lock)
  bb.buf[bb.in mod N] <- message</pre>
  bb.in < bb.in + 1
  release(bb.lock)
 notify(bb.has_message)
  return
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condition variable API:

- wait(cv,lock): yield processor, release lock, wait to be notified Of CV
- notify(cv): notify waiting threads of cv







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  bb.buf[bb.in mod N] <- message</pre>
  bb.in < bb.in + 1
  release(bb.lock)
  notify(bb.has_message)
  return
```

our second job today is to understand how wait() and **notify()** work, and also where **yield()** ends up in all of this

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t_lock makes yield() and wait() atomic
actions

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```
wait(cv, lock):
    acquire(t_lock)
    // release lock
```

// set current thread to be
// waiting on cv

// yield

release(t_lock)
// re-acquire lock



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release(t_lock)
acquire(lock)



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```

```
wait(cv, lock):
    acquire(t_lock)
    release(lock)
    id = cpus[CPU].thread
    threads[id].cv = cv
    threads[id].state = WAITING
    // yield
    release(t_lock)
    acquire(lock)
```



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```
wait(cv, lock):
    acquire(t_lock)
    release(lock)
    id = cpus[CPU].thread
    threads[id].cv = cv
    threads[id].state = WAITING
    yield_wait()
    release(t_lock)
    acquire(lock)
```



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wait(cv, lock):
    acquire(t_lock)
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    id = cpus[CPU].thread
    threads[id].cv = cv
    threads[id].state = WAITING
    yield_wait()
    release(t_lock)
    acquire(lock)
```

for right now, you can assume that yield_wait() is the same as yield()

we're giving it a different name, because we're going to find that it needs to be a slightly different function



can wait on a condition, and be **notified** of it occurring

```
notify(cv):
  acquire(t_lock)
  for id = 0 to N-1:
    if threads[id].cv == cv &&
       threads[id].state == WAITING:
      threads[id].state = RUNNABLE
  release(t_lock)
```

notify(cv) finds all threads waiting on **cv**, and sets their state to RUNNABLE (i.e., ready to be run; not RUNNING)

> we're going to get back to yield wait() in a second, but just for context, here's how notify() works

condition variables let threads wait for events ("conditions"), and get notified when they occur

wait(cv, lock): acquire(t_lock) release(lock) id = cpus[CPU].thread threads[id].cv = cv threads[id].state = WAITING yield_wait() release(t_lock) acquire(lock)



but let's find out why it needs to be slightly different



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  yield_wait()
  release(t_lock)
  acquire(lock)
```

```
yield_wait():
  acquire(t_lock)
```

```
// Suspend the running thread
id = cpus[CPU].thread
threads[id].state = RUNNABLE
threads[id].sp = SP
threads[id].ptr = PTR
```

```
// Choose a new thread to run
do:
  id = (id + 1) \mod N
```

while threads[id].state != RUNNABLE

```
// Resume the new thread
SP = threads[id].sp
PTR = threads[id].ptr
threads[id].state = RUNNING
cpus[CPU].thread = id
```

```
release(t_lock)
```



but let's find out why it needs to be slightly different

wait(cv, lock): acquire(t_lock) release(lock) id = cpus[CPU].thread threads[id].cv = cv threads[id].state = WAITING yield_wait() release(t_lock) acquire(lock)

problem: wait() holds t_lock

```
yield_wait():
 acquire(t_lock)
```

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// Choose a new thread to run do:

```
// Resume the new thread
SP = threads[id].sp
PTR = threads[id].ptr
threads[id].state = RUNNING
cpus[CPU].thread = id
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release(t_lock)
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  release(t_lock)
  acquire(lock)
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yield_wait():
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 // Choose a new thread to run
 do:
    id = (id + 1) \mod N
 while threads[id].state != RUNNABLE
  // Resume the new thread
  SP = threads[id].sp
  PTR = threads[id].ptr
 threads[id].state = RUNNING
  cpus[CPU].thread = id
```



but let's find out why it needs to be slightly different

```
wait(cv, lock):
  acquire(t lock)
  release(lock)
  id = cpus[CPU].thread
  threads[id].cv = cv
         [id].state = WAITING
  yield_wait()
  release(t_lock)
  acquire(lock)
```

problem: current thread's state shouldn't be set to RUNNABLE (wait() has already set it to WAITING)

```
yield_wait():
  // Suspend the running thread
  id = cpus[CPU].thread
  chreads[id].state = RUNNABLE
 threads[id].sp = SP
 threads[id].ptr = PTR
  // Choose a new thread to run
  do:
    id = (id + 1) \mod N
 while threads[id].state != RUNNABLE
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  SP = threads[id].sp
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yield_wait(): // Suspend the running thread id = cpus[CPU].thread threads[id].sp = SP threads[id].ptr = PTR // Choose a new thread to run do: $id = (id + 1) \mod N$ while threads[id].state != RUNNABLE // Resume the new thread SP = threads[id].sp PTR = threads[id].ptr threads[id].state = RUNNING cpus[CPU].thread = id



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```

problem: deadlock

(wait() holds t_lock, but notify() also needs it)

yield_wait(): // Suspend the running thread id = cpus[CPU].thread threads[id].sp = SP threads[id].ptr = PTR // Choose a new thread to run do: $id = (id + 1) \mod N$ while threads[id].state != RUNNABLE // Resume the new thread SP = threads[id].sp PTR = threads[id].ptr threads[id].state = RUNNING cpus[CPU].thread = id



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```

problem: stack corruption

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yield_wait():
 // Suspend the running thread
 id = cpus[CPU].thread
 threads[id].sp = SP
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 do:
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  yield_wait()
  release(t_lock)
  acquire(lock)
```

```
yield_wait():
  // Suspend the running thread
 id = cpus[CPU].thread
 threads[id].sp = SP
 threads[id].ptr = PTR
 SP = cpus[CPU].stack
  // Choose a new thread to run
  do:
    id = (id + 1) \mod N
    release(t_lock)
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 while threads[id].state != RUNNABLE
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  SP = threads[id].sp
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we've done so much work. but what if threads just never call wait() (or yield())?



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preemption: forcibly interrupt threads





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timer_interrupt(): push PC push registers yield() pop registers

pop PC



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> **solution:** hardware mechanism to disable interrupts

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> **solution:** hardware mechanism to disable interrupts

we've done so much work. but what if threads just never call wait() (or yield())?

timer_interrupt(): push PC push registers yield() pop registers pop PC

notice the need for some assistance from hardware here! just like how we required an atomic exchange operation for locks, and how we require the physical addresses of the page table registers for virtual memory to work

(and also similar to how the IP addresses of the DNS root servers are hardcoded into clients)



```
yield():
    acquire(t_lock)
```

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first-come first-serve: whichever thread yielded

first is scheduled first



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priority scheduling: threads that *need* to finish sooner are scheduled before threads that can be scheduled later



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round robin: assign a *quantum* of time per thread, and schedule threads to get one quantum in a "round robin" order; repeat as needed



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```

```
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```

how threads are scheduled has a large **impact** on performance and **fairness**; there is no *best* scheduling algorithm

first-come first-serve: whichever thread yielded first is scheduled first

priority scheduling: threads that *need* to finish sooner are scheduled before threads that can be scheduled later

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operating systems enforce modularity on a single machine

in order to enforce modularity + have an effective operating system, a few things need to happen

- 1. programs shouldn't be able to refer to (and corrupt) each others' **memory**
- 2. programs should be able to **communicate** with each other
- 3. programs should be able to share a **CPU** without one program halting the progress of the others

virtualize memory

bounded buffers

(virtualize communication links)

threads (virtualize processors)



threads virtualize a processor so that we can share it among programs. yield() allows the kernel to suspend the current thread and resume another



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condition variables provide a more efficient API for threads, where they wait for an event and are notified when it occurs. wait() requires a new version of yield(), yield_wait()



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threads, where they wait for an event and are notified
when it occurs. wait() requires a new version of
yield(), yield_wait()

preemption forces a thread to be interrupted so that the kernel doesn't have to rely on programmers correctly using yield(). requires a special interrupt and hardware support to disable other interrupts

