

6.251/15.081J Computational Assignment*

Massachusetts Institute of Technology

Due: November 4, 2002

Exercise 1. *The affine scaling algorithm.*

- (a) Implement in MATLAB a function `affscale.m` which performs the affine scaling algorithm (as per p.400 in [1]). The prototype for the function is

```
[xstar,ubflag,fconv,xconv] = affscale(A,b,c,x0,tol,beta),
```

where the inputs `A`, `b`, and `c` are the usual (standard form) LP parameters, `x0` is an initial feasible solution, `tol` is the optimality tolerance, and `beta` is the step-length scale factor. The outputs are an optimal solution (if found) `xstar`, as well as the flag `ubflag`, which is 1 if the problem is detected to be unbounded and 0 otherwise. The last outputs are `fconv`, which is a vector storing the objective value of the feasible solution \mathbf{x}^k at each iteration, and `xconv`, which is a matrix with column k being \mathbf{x}^k . Print out and submit a copy of your code.

- (b) Solve the LP $\min\{-x_1 - 3x_2 : x_1 + x_2 \leq 1, x_1, x_2 \geq 0\}$. Obviously, you must convert to standard form first.
- (c) For the LP in (b), print out a convergence plot (from your vector `fconv`) of the objective value for `beta=0.01`, `beta=0.50`, and `beta=0.99`. Use the same `x0` and `tol` in each case and provide a qualitative explanation for any observed differences.
- (d) For the LP in (b), solve it twice with your code, once for `x0=1/3*[1;1;1]` and once for `x0=[0.99;0.005;.005]` (last component is the slack variable). For both runs, make a scatter plot of the first two components of all of the \mathbf{x}^k solutions, which are stored in `xconv`. Use the same `beta` and `tol` in both cases and provide a qualitative explanation for any observed differences. [*Hint:* To make a scatter plot of two vectors `x` and `y`, use the command `plot(x,y,'+')`.]

*For those students unfamiliar with MATLAB, please see the short primer linked to on the course website.

Exercise 2. *An example LP.*

- (a) Solve exercise 5.6(b) in [1] using your algorithm from exercise 1. Print out a convergence plot of the objective value and make sure to note what values of the various parameters you used, as well as the optimal solution.
- (b) Solve exercises 5.6(c)-(g) in [1] using a standard LP solver. The course staff highly recommends the function `linprog.m` in MATLAB, but you are free to choose any available tools.

References

- [1] Bertsimas, D.; Tsitsiklis, J.N. *Introduction to Linear Optimization*. Athena Scientific, 1997.