

5.73 Lecture #3

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Reading Chapter 1, CTDL, pages 9-39, 50-56, 60-85

Last time: 1. 1-D infinite box

continuity of $\psi(x), \frac{d\psi}{dx}, \frac{d^2\psi}{dx^2}$

confinement \rightarrow quantization

$$E_n = n^2 \left[\frac{\hbar^2}{8mL^2} \right]$$

$$\psi_n = (2/L)^{1/2} \sin(n\pi x)$$

2. δ -function well

one bound level

$$E = \frac{-ma^2}{2\hbar^2}$$

$$\psi = \pm \left(\frac{ma}{\hbar^2} \right)^{1/2} e^{-ma|x|/\hbar^2} \quad (\text{what happens to } \psi \text{ as } a \text{ increases?})$$

Why do we know there is only one bound level?

What do we know about $\bar{\psi}(p)$? How does this depend on a? what about $\langle p \rangle$?

TODAY and WEDNESDAY:

1. motion \rightarrow time dependent Schr. Eq.
2. motion of constant phase point on $\Psi(x,t)$ -- phase velocity
3. motion of $|\Psi(x,t)|^2$ requires non-sharp E
4. encode $\Psi(x,t)$ for $x_0, \Delta x, p_0, \Delta p$
5. $p_0, \Delta p$ from $|g(k)|$
6. $x_0, \Delta x$ from stationary phase argument
7. moving, spreading wavepacket $|\Psi(x,t)|^2$
8. group velocity \neq phase velocity -- see CTDL, pages 28-31

1. Motion

time dependent Schr. Eq. $i\hbar \frac{\partial \Psi}{\partial t} = \mathbf{H}\Psi$ TDSE

if $V(x)$ is time independent, then

$$\Psi_n(x, t) = \psi_n(x)e^{-iE_n t/\hbar}$$

satisfies TDSE?

can use this form of Ψ to describe time dependence of any non-eigenstate initial preparation: e.g. wavepackets

$$\Psi(x, 0) = \sum a_n \psi_n(x) \quad \text{superposition of eigenstates}$$

$$\Psi(x, t) = \sum a_n \psi_n(x)e^{-i\omega_n t} \quad \omega_n = E_n/\hbar$$

go back to free particle to really see motion of QM systems

$$\psi_{|k|}(x) = Ae^{ikx} + Be^{-ikx}$$

$$E_k - V_0 = \frac{\hbar^2 k^2}{2m} = \frac{p^2}{2m}$$

$$\omega_k = (E_k - V_0)/\hbar = \frac{\hbar k^2}{2m} \geq 0$$

add a phase factor which expresses the arbitrariness of the zero of energy:

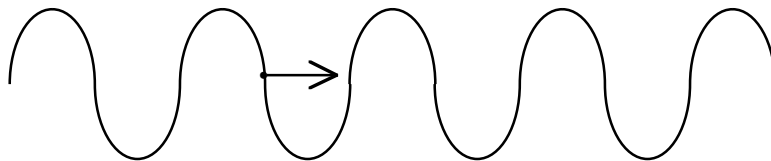
WHAT ABOUT
ARBITRARY
ZERO OF E?
CALL IT E_0

$$\begin{aligned} \Psi_{|k|}(x, t) &= e^{-i\omega_k t} [Ae^{ikx} + Be^{-ikx}] e^{-iE_0 t/\hbar} \\ &= [Ae^{i(kx - \omega_k t)} + Be^{-i(kx + \omega_k t)}] e^{-iE_0 t/\hbar} \end{aligned}$$

2. How does point of constant ^[argument]_{phase} move?

$$\text{const} = kx_\phi - \omega_k t$$

$$x_\phi(t) = + \frac{\omega_k t}{k} + x_\phi(0) \quad \text{moves in +x direction if } k > 0$$



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$$v_\phi = \frac{dx_\phi}{dt} = \frac{\omega_k \leftarrow \frac{\hbar k^2}{2m}}{k} \quad \text{phase velocity} \quad v_\phi = \frac{\hbar k}{2m} = \frac{p}{2m} = \frac{v}{2} \quad \text{(half as fast as we naively expect)}$$

first term in $\Psi(x,t)$ moves to $+x$ (right), second to $-x$ (left).

But if we treat the $e^{-iV_0 t/\hbar} = e^{-i\omega_0 t}$ term explicitly,

we get $v_\phi = \frac{\omega_k + \omega_0}{k}$! Any velocity we want! IS THIS A PROBLEM? WHY NOT?

(compare v_ϕ for a $+k, -k$ pair of free particle states)

3. But what about the probability distribution, $\mathbf{P}(x,t)$?

$$\mathbf{P}(x,t) = \Psi^*(x,t)\Psi(x,t) = |A|^2 + |B|^2 + 2\text{Re}(A^* B)\cos 2kx + 2\text{Im}(A^* B)\sin 2kx$$

no time dependence! lose all t -dependence because cross terms ($+k, -k$) still belong to same E_k ! The wiggles in $\Psi^* \Psi$ are standing waves, not traveling waves. No ambiguity about V_0 either?

What is the expectation value of \hat{p} $\langle p \rangle = \frac{\int \Psi^* \hat{p} \Psi dx}{\int \Psi^* \Psi dx}$?

$$\langle p \rangle = \hbar k \frac{|A|^2 - |B|^2}{|A|^2 + |B|^2}$$

This is an interesting result that suggests something that is always true and a very useful inspection tool. Whenever the wavefunction is pure real or pure imaginary, $\langle p \rangle = 0$.

SO HOW DO WE ENCODE $\Psi(x,t)$ for *both* spatial localization *and* temporal motion? need several k components, not just $+k, -k$

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****4. Recipe for encoding Gaussian Wavepacket for $x_0, \Delta x, p_0, \Delta p$**

Start with $\Psi(x,0)$ and later build in correct $e^{-i\omega_k t}$ dependence for each k component.

THIS IS GOING TO BE SHOWN TO BE the Ψ that yields $\Psi^* \Psi$ as a Gaussian prob. distrib. in x and p

$$\Psi(x, 0) = \frac{a^{1/2}}{(2\pi)^{3/4}} \int_{-\infty}^{\infty} \underbrace{e^{-(a^2/4)(k-k_0)^2}}_{g(k)} e^{ikx} dk$$

FT of a Gaussian

*form of a Gaussian in k
* superposition of many e^{ikx}

WHAT KIND OF FUNCTION IS THE SQUARE OF A GAUSSIAN? WHAT IS ITS WIDTH?

ASIDE
see Gaussian Handout

a Gaussian prob. distrib. in x $G(x; x_0, \Delta x) \equiv (2\pi)^{-1/2} \frac{1}{\Delta x} e^{-(x-x_0)^2 / [2(\Delta x)^2]}$

G is normalized $\int_{-\infty}^{\infty} G(x; x_0, \Delta x) dx = 1$

$\langle x \rangle = x_0$
 $\langle x^2 \rangle = (\Delta x)^2 + x_0^2$ $(\Delta x)^2$ is called the variance in x
 $[\langle x^2 \rangle - \langle x \rangle^2]^{1/2} \equiv \Delta x$

4A. $\underline{k}_0, \underline{\Delta k}$.

Now what can we say about $g(k)$ in $\Psi(x,0)$ above?

$$G(k; k_0, \Delta k) = (2\pi)^{-1/2} \left(\frac{a}{2^{1/2}} \right) g(k)$$

$$\frac{a^2}{4} \longleftrightarrow \frac{1}{2(\Delta x)^2}$$

$$\therefore \frac{a}{2^{1/2}} \longleftrightarrow \frac{1}{\Delta x}$$

$$g(k) = e^{-(a^2/4)(k-k_0)^2}$$

compared to

$$G(x; x_0, \Delta x) = (2\pi)^{-1/2} \frac{1}{\Delta x} e^{-(x-x_0)^2/[2(\Delta x)^2]}$$

$$\therefore \langle k \rangle = k_0$$

$$\Delta k = (2^{1/2}/a)$$

you can verify
by doing
relevant
integrals

So we already know, by inspection (rather than integration), the $k_0, \Delta k$ parts for $\psi(x,0)$.

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4B. What about $x_0, \Delta x$ for $G(k; k_0, \Delta k)$?

To do this, perform the FT implicit in defn. of $\Psi(x, 0)$ [CTDL, pages 61-62]

$$\Psi(x, 0) = \frac{a^{1/2}}{(2\pi)^{3/4}} \int_{-\infty}^{\infty} e^{-(a^2/4)(k-k_0)^2 + ikx} dk$$

complete the squares in the exponent (because Gaussian integrals are easy)

$$-(a^2/4)(k-k_0)^2 + ikx = -\frac{a^2}{4} \left[(k-k_0) - \frac{2ix}{a^2} \right]^2 + ik_0x - \frac{x^2}{a^2}$$

k-dependent → change variables and evaluate Gaussian integral
k-independent — take outside integral

result $\Psi(x, 0) = \left(\frac{2}{\pi a^2} \right)^{1/4} e^{ik_0x} e^{-x^2/a^2}$ FT of a Gaussian is a Gaussian!

$\langle x \rangle = \langle x_0 \rangle = 0$

$\Delta x = 2^{-1/2} a$

$(2^{1/2}/a)$ (for $\Psi * \Psi$, $\Delta x = a/2$, $\Delta k = \frac{1}{a}$, and $\Delta x \Delta k = 1/2$)

ALL OF THE $k_0, \Delta k$ INFORMATION IS HIDDEN

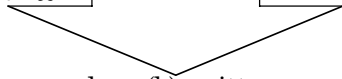
$\Delta x \Delta k = 1 \quad \Delta x \Delta p = \hbar$ minimum uncertainty!

- This wavepacket: 1. minimum uncertainty
2. centered at $x_0 = 0$

5,6. How to build a w.p. (not necessarily Gaussian) centered at arbitrary x_0 with arbitrary Δx ?

* Start again with a new $g(k)$

$$\Psi(x, 0) = \frac{a^{1/2}}{(2\pi)^{3/4}} \int_{-\infty}^{\infty} \boxed{|g(k)| e^{i\alpha(k)}} e^{ikx} dk$$


 complex $g(k)$ written
in amplitude,
argument form

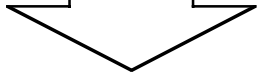
5. let $|g(k)|$ be sharply peaked near $k = k_0$. [It could be $e^{-(a^2/4)(k-k_0)^2}$ and then we already know k_0 and $\Delta k = 2^{1/2}/a$.]
6. Thus we really only need to look at $\alpha(k)$ near k_0 in order to find info about $\langle x \rangle$ and Δx . This is a very important simplification (or focussing of attention)!

Stationary phase argument

 **

Expand in $\alpha(k)$ in power series in $(k-k_0)$

$$\alpha(k) \cong \boxed{\alpha(k_0)} + (k - k_0) \left. \frac{d\alpha}{dk} \right|_{k=k_0}$$


 α_0

Thus the exponential in integral becomes

$$e^{i\alpha_0} e^{i \left[(k-k_0) \frac{d\alpha}{dk} + kx \right]}$$

very wiggly function of x except at a special region of x

Now what we want to know is the value of x (for k near k_0) where the phase factor becomes independent of k . This is because, when we integrate over k , if the wiggly factor in the integrand stops wiggling, the integral accumulates to its final value near this value of k !

plot $I(k)$ vs. k

$$I(k) = \int_{-\infty}^k (\text{integrand}) dk$$

The value of the integral evaluated at this special value of x (that we do not yet know) $x = x_0(\bar{t})$ is $\sim g(k_0) \delta k$ where δk is the change in k required to cause the phase factor to change by π .

**MOST
IMPORTANT
IDEA IN THE
ENTIRE
LECTURE!**

Solve for value of x where the phase factor stops changing, i.e. take derivative with respect to k to find extremum.

$$\frac{d}{dk} \left[\underbrace{(k-k_0) \frac{d\alpha}{dk} + kx}_{\text{phase factor}} \right] = 0$$

↑
stationary phase requirement

$$\therefore \text{ want } \frac{d\alpha}{dk} + x = 0$$

If we let $\left. \frac{d\alpha}{dk} \right|_{k=k_0} \equiv -x_0$, then the phase factor is stationary when x is near x_0

$$\Psi(x, 0) = \frac{a^{1/2}}{(2\pi)^{3/4}} \int_{-\infty}^{\infty} e^{-\left(a^2/4\right)(k-k_0)^2} \underbrace{e^{-i(k-k_0)x_0} e^{ikx}}_{= \underbrace{e^{-ik(x-x_0)}}_{\delta(x, x_0)} e^{ik_0x_0}} dk$$

shifts Ψ to be sharply peaked at any x_0 \longrightarrow

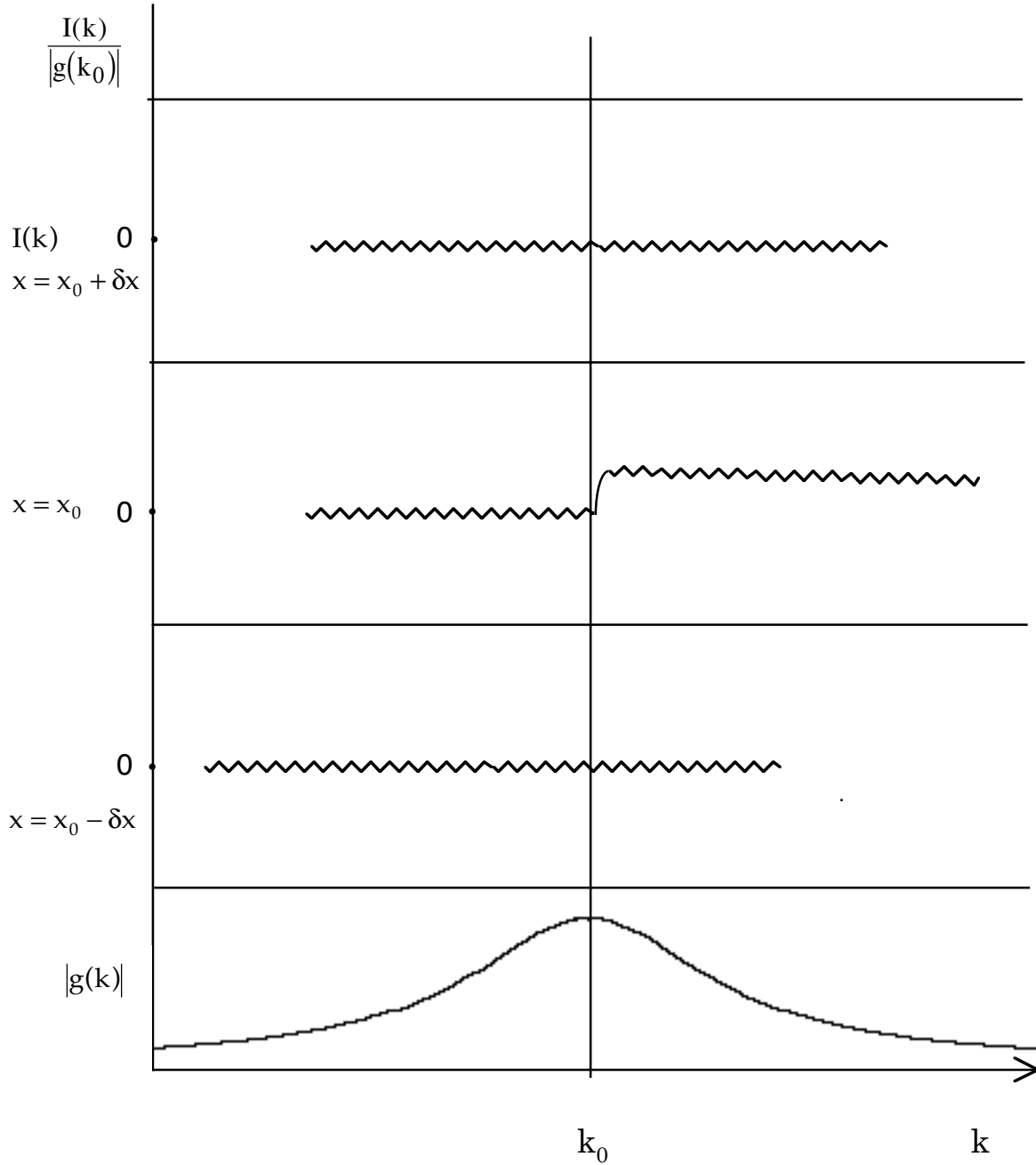
This $|\Psi|^2$ is localized at x_0, k_0 , and has widths $\Delta x, \Delta k$,

$\Delta k = ?$ (easy: by inspection)

$\Delta x = ?$ (must perform Fourier transform)

This prescription does not permit free specification of Δx . Δx must still be $\Delta x = 2^{-1/2}a$ if $|g(k)|$ is a Gaussian [shortcut: $\Delta x \Delta k = 1$].

[N.B. We are talking about the shape of $\Psi(x, 0)$, not the QM Δx and Δp associated with a particular Ψ .]



Integral accumulates near $k = k_0$ but only when $x \approx x_0$.

7. Now we are ready to let $\Psi(x,t)$ evolve in time

$$\Psi(x,t) = \frac{a^{1/2}}{(2\pi)^{3/4}} \int_{-\infty}^{\infty} |g(k)| e^{-i(k-k_0)x_0} e^{ikx} e^{-i\omega_k t} dk$$

$$\omega_k = \frac{E_k}{\hbar} = \boxed{\frac{\hbar^2 k^2}{2m\hbar} = \frac{\hbar k^2}{2m}}$$

SPECIAL CHOICE OF ZERO OF E, $V_0 = 0$

See CTDL, page 64 for evaluation of $\int dk$ integral and simplification of $\Psi(x,t)$ and $|\Psi(x,t)|^2$. Arbitrary choice of zero of E drops out of $|\Psi(x,t)|^2$.

$$|\Psi(x,t)|^2 = \underbrace{\left(\frac{2}{\pi a^2}\right)^{1/2} \left(1 + \frac{4\hbar^2 t^2}{m^2 a^4}\right)^{-1/2}}_{\text{t-dependent normalization factor}} \exp\left[-\frac{2a^2 \left(x - \frac{\hbar k_0 t}{m}\right)^2}{a^4 + \frac{4\hbar^2 t^2}{m^2}}\right]$$

spreading

- Complicated:
- * Δx depends on t, reaching minimum value when $t = 0$
 - * x_{0t} , the center of the wavepacket, moves as

$$x_{0t} = \underbrace{\frac{\hbar k_0}{m}}_{v_{\text{group}} \neq v_{\text{phase}}} t = \frac{\hbar k_0}{2m}!$$

* $|g(k)|$, which is independent of time, contains all info about $p_0, \Delta p$.

Therefore these quantities do not evolve in time for a free wavepacket. They do evolve if $V(x)$ is not constant.

Think about chopping up the Fourier transform of $|\Psi(x,t)|^2$ into pieces corresponding to different values of p . If there is no force acting on the wavepacket, the $\langle p \rangle$ for each piece of the original $|\Psi(x,t)|^2$ remains constant.

Summary

We know how to encode a wavepacket for $p_0, \Delta p, x_0$ (and since Δx is an explicit function of time, we can let $\Psi(x,t)$ evolve until it has the desired Δx and then shift x_{0t} back to the desired location where Δx has the now specified value).

We also know how to inspect an arbitrary Gaussian $\Psi(x,t)$ to reveal its $x_{0t}, \Delta x, p_{0t}, \Delta p$ without evaluating any integrals.