

Solutions Mechanics I SPRING 2001

Kinetic energy

$$T = \frac{m_1}{2} (\dot{x}_D^2 + \dot{y}_D^2) + \frac{I}{2} \dot{\varphi}_1^2 + \frac{m_2}{2} (\dot{x}_C^2 + \dot{y}_C^2)$$

Potential energy

$$V = -m_1 g y_D - m_2 g y_C$$

Geometry

$$x_D = a \sin \varphi_1 \quad y_D = a \cos \varphi_1$$

$$x_C = b \sin \varphi_1 + c \sin \varphi_2 \quad y_C = b \cos \varphi_1 + c \cos \varphi_2$$

$$\mathcal{L} = T - V$$

$$\mathcal{L} = \frac{\dot{\varphi}_1^2}{2} (m_1 a^2 + I + m_2 b^2) + \frac{\dot{\varphi}_2^2}{2} \cdot m_2 c^2$$

$$+ m_2 b c \dot{\varphi}_1 \dot{\varphi}_2 \cos(\varphi_1 - \varphi_2)$$

$$+ (m_1 a + m_2 b) g \cos \varphi_1 + m_2 c g \cos \varphi_2$$

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{\varphi}_1} \right) = \frac{\partial \mathcal{L}}{\partial \varphi_1} \quad (1)$$

$$(m_1 a^2 + I + m_2 b^2) \ddot{\varphi}_1 + m_2 b c \ddot{\varphi}_2 \cos(\varphi_1 - \varphi_2) + m_2 b c \dot{\varphi}_2^2 \sin(\varphi_1 - \varphi_2) = - (m_1 a + m_2 b) g \sin \varphi_1$$

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{\varphi}_2} \right) = \frac{\partial \mathcal{L}}{\partial \varphi_2} \quad (2)$$

$$m_2 c^2 \ddot{\varphi}_2 + m_2 b c \dot{\varphi}_1 \cos(\varphi_1 - \varphi_2) - m_2 b c \dot{\varphi}_1^2 \sin(\varphi_1 - \varphi_2) = - m_2 c g \sin \varphi_2$$

Simultaneous motion $\varphi_1 = \varphi_2 = \varphi$ $\cos(\varphi_1 - \varphi_2) = 1$
 $\sin(\varphi_1 - \varphi_2) = 0$

$$(1) : (m_1 a^2 + I + m_2 b^2 + m_2 b c) \ddot{\varphi} = - (m_1 a + m_2 b) g \sin \varphi$$

$$(2) : (m_2 c^2 + m_2 b c) \ddot{\varphi} = - m_2 c g \sin \varphi$$

These two equations are satisfied simultaneously if

$$\frac{m_2 c^2 + m_2 b c}{m_1 a^2 + m_2 b^2 + m_2 b c + I} = \frac{m_2 c g}{(m_1 a + m_2 b) g}$$

$$\text{or } \frac{(m_1 a + m_2 b)(b + c)}{m_1 a^2 + m_2 b^2 + m_2 b c + I} = 1$$

Solutions Mechanics 2

$x_1, x_2, x_3 \rightarrow$ deviation from equilibrium

$$\mathcal{L} = \frac{m}{2} (\dot{x}_1^2 + \dot{x}_2^2 + \dot{x}_3^2) - \frac{k}{2} \left((x_1 - x_2)^2 + (x_2 - x_3)^2 + (x_3 - x_1)^2 \right)$$

EQM of motion:

$$m \ddot{x}_1 = -k(x_1 - x_2) + k(x_3 - x_1)$$

$$m \ddot{x}_2 = +k(x_1 - x_2) - k(x_2 - x_3)$$

$$m \ddot{x}_3 = +k(x_2 - x_3) - k(x_3 - x_1)$$

Assume $x_i = A_i \cos(\omega t + \varphi)$

$$\begin{pmatrix} 2k - m\omega^2 & -k & -k \\ -k & 2k - m\omega^2 & -k \\ -k & -k & 2k - m\omega^2 \end{pmatrix} \begin{pmatrix} A_1 \\ A_2 \\ A_3 \end{pmatrix} = 0$$

$$\text{Det}(M) = 0 \quad \left(\frac{m\omega^2}{k} \right) \left(\frac{m\omega^2}{k} - 3 \right)^2 = 0$$

$$\omega_1 = 0 \quad \omega_2 = \omega_3 = \sqrt{\frac{3k}{m}}$$

$$\omega_1 = 0 \Rightarrow x_1 = x_2 = x_3 \quad x_i(t) = at + b$$

Normal Coordinates:

$$q = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$q_1 = \begin{pmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{pmatrix} (at+b)$$

q_2, q_3 are as many as necessary \rightarrow orthogonal to q_1 and orthogonal to each other. For example

$$q_2 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \end{pmatrix} \cos(\omega t + \varphi) \quad q_3 = \begin{pmatrix} \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \\ -\frac{2}{\sqrt{6}} \end{pmatrix} \cos(\omega t + \varphi)$$

$$x_1(t) = \left(\frac{1}{\sqrt{3}} q_1 + \frac{1}{\sqrt{2}} q_2 + \frac{1}{\sqrt{6}} q_3 \right) A_1$$

$$x_2(t) = \left(\frac{1}{\sqrt{3}} q_1 - \frac{1}{\sqrt{2}} q_2 + \frac{1}{\sqrt{6}} q_3 \right) A_2$$

$$x_3(t) = \left(\frac{1}{\sqrt{3}} q_1 \quad \quad \quad -\frac{2}{\sqrt{6}} q_3 \right) A_3$$

Initial conditions:

$$x_1(t=0) = \delta \quad x_2 = x_3 = 0$$

$$\dot{x}_1 = \dot{x}_2 = \dot{x}_3 = 0$$

$$q(t=0) = \begin{pmatrix} \delta \\ 0 \\ 0 \end{pmatrix} \quad \dot{q}(t=0) = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \begin{array}{l} \varphi = 0 \\ \alpha = 0 \\ b = 1 \end{array}$$

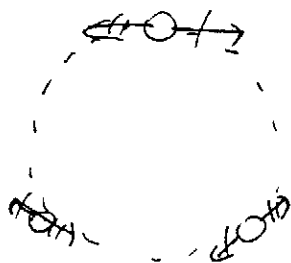
$$q(t) = \frac{\delta}{\sqrt{3}} \cdot q_1(t) + \frac{\delta}{\sqrt{2}} q_2(t) + \frac{\delta}{\sqrt{6}} \cdot q_3(t)$$

$$q(t=0) = \begin{pmatrix} \delta \\ 0 \\ 0 \end{pmatrix} \quad \dot{q}(t=0) = 0 \quad \text{O.K.}$$

$$\begin{aligned} x_1(t) &= \frac{1}{\sqrt{3}} \frac{\delta}{3} + \frac{1}{\sqrt{2}} \frac{\delta}{\sqrt{2}} \cos(4t) + \frac{1}{\sqrt{6}} \frac{\delta}{\sqrt{6}} \cos(4t) \\ &= \frac{\delta}{3} + \frac{2\delta}{3} \cos(4t) \end{aligned}$$

$$x_2(t) = \frac{\delta}{3} - \frac{\delta}{3} \cos(4t)$$

$$x_3(t) = \frac{\delta}{3} - \frac{\delta}{3} \cos(4t)$$



$\vec{E} \perp \vec{M} \perp$ Solutions

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} \quad \vec{B} = \mu_0 (\vec{H} + \vec{M})$$

$$\vec{P} = \gamma \vec{\nabla} \times \vec{E} \quad \vec{M} = 0$$

$$\vec{D} = \epsilon_0 \vec{E} + \gamma \vec{\nabla} \times \vec{E} \quad \vec{B} = \mu_0 \vec{H}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \frac{\partial \vec{D}}{\partial t} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \mu_0 \gamma \vec{\nabla} \times \left(\frac{\partial \vec{E}}{\partial t} \right)$$

$$\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \quad \vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = - \vec{\nabla} \times \left(\frac{\partial \vec{B}}{\partial t} \right)$$
$$- \nabla^2 \vec{E} + \vec{\nabla} (\vec{\nabla} \cdot \vec{E})$$

0

$$- \nabla^2 \vec{E} = - \underbrace{\mu_0 \epsilon_0}_{\frac{1}{c^2}} \frac{\partial^2 \vec{E}}{\partial t^2} - \gamma \mu_0 \vec{\nabla} \times \left(\frac{\partial^2 \vec{E}}{\partial t^2} \right)$$

Plane wave

$$\vec{E} = \vec{E}_0 e^{i(kz - \omega t)} = E_x \hat{x} + E_y \hat{y}$$

$$k^2 \vec{E} = \frac{\omega^2}{c^2} \vec{E} + i \gamma \mu_0 \omega^2 k (\hat{z} \times \vec{E})$$

Component equations:

$$\left(k^2 - \frac{\omega^2}{c^2}\right) E_x + i \gamma \mu_0 \omega^2 k \cdot E_y = 0$$

$$-i \gamma \mu_0 \omega^2 k \cdot E_x + \left(k^2 - \frac{\omega^2}{c^2}\right) E_y = 0$$

Non zero solutions if:

$$\left(k^2 - \frac{\omega^2}{c^2}\right)^2 - \gamma^2 \mu_0^2 \omega^4 k^2 = 0$$

$$k^2 - \frac{\omega^2}{c^2} = \pm \gamma \mu_0 \omega^2 k$$

$$k^2 \mp \gamma \mu_0 \omega^2 \cdot k - \frac{\omega^2}{c^2} = 0$$

$$k = \frac{1}{2} \left[\pm \gamma \mu_0 \omega^2 \pm \sqrt{\gamma^2 \mu_0^2 \omega^4 + \frac{4\omega^2}{c^2}} \right]$$

Choose $k > 0$ only

$$k_{\pm} = \frac{1}{2} \left[\pm \gamma \mu_0 \omega^2 + \sqrt{\gamma^2 \mu_0^2 \omega^4 + \frac{4\omega^2}{c^2}} \right]$$

$$n_{\pm} = \frac{c}{\omega} k_{\pm} = \pm \frac{\gamma c \mu_0 \omega}{2} + \sqrt{1 + \frac{(\gamma c \mu_0 \omega)^2}{2}}$$

$$n_{\pm} \approx 1 \pm \frac{\gamma c \mu_0 \omega}{2}$$

Fields that diagonalize the component
matrix are circularly polarized waves

$$E_+ = E_x + i E_y \quad \text{right-handed}$$

$$E_- = E_x - i E_y \quad \text{left-handed}$$

E & M Solutions 2

$$\vec{E}(r \rightarrow \infty) = E_0 \hat{z} = E_0 (\hat{r} \cos \theta - \hat{\theta} \sin \theta)$$

Potential that will satisfy all boundary conditions is

$$V(r, \theta) = \frac{A}{r} + \left(Br + \frac{C}{r^2} \right) \cos \theta$$

$$\vec{E} = -\vec{\nabla} V = \frac{A}{r^2} \hat{r} - \left(B - \frac{2C}{r^3} \right) \cos \theta \cdot \hat{r} + \left(B + \frac{C}{r^3} \right) \sin \theta \cdot \hat{\theta}$$

$$r \rightarrow \infty \quad B = -E_0$$

$$V(r=R) = \text{const} \Rightarrow BR + \frac{C}{R^2} = 0$$

θ independent

$$C = E_0 \cdot R^3$$

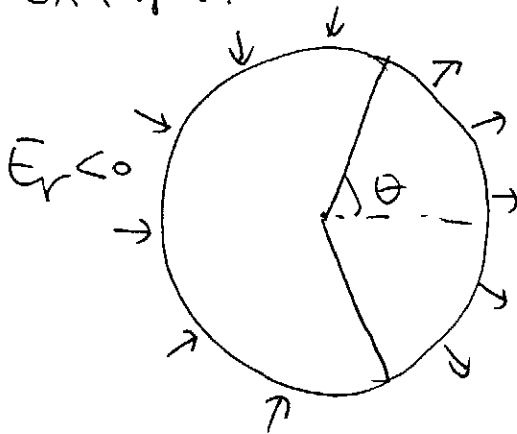
$$A = \frac{Q}{4\pi\epsilon_0}$$

$$\vec{E} = \left[\frac{Q}{4\pi\epsilon_0 r^2} + E_0 \left(1 + \frac{2R^3}{r^3} \right) \cos \theta \right] \hat{r} - \left[E_0 \left(1 - \frac{R^3}{r^3} \right) \sin \theta \right] \hat{\theta}$$

at $r = R$

$$\vec{E} = \underbrace{\left[\frac{Q}{4\pi\epsilon_0 R^2} + 3E_0 \cos\theta \right]}_{E_r} \hat{r}$$

Example:



$$E_r < 0 \quad \text{if} \quad \frac{Q}{4\pi\epsilon_0 R^2} + 3E_0 \cos\theta < 0$$

$$-1 \leq \cos\theta \leq 1$$

$$Q > 12 E_0 \pi \epsilon_0 R^2 = Q_{\max} \quad E_r < 0 \quad \boxed{\text{Never!}}$$

$$Q < -Q_{\max} \quad E_r < 0 \quad \boxed{\text{Always}}$$

$$-Q_{\max} < Q < Q_{\max} \quad E_r = 0 \quad \boxed{\text{if } \cos\theta < -\frac{Q}{Q_{\max}}}$$

c) $Q_0 < Q_{\max} = 12 \epsilon_0 \pi \epsilon_0 R^2$ Most have $E_r < 0$ for the dust to lead surface

d) $j_r = \rho_0 \mu E_r (r=R)$
 $= 3 \rho_0 \mu \epsilon_0 \left(\frac{Q}{Q_{\max}} + \cos \theta \right) \quad (E_r < 0!)$

e) ① $Q < -Q_{\max} \quad E_r < 0$ everywhere!
 $-1 \leq \cos \theta \leq 1$

$$\frac{dQ}{dt} = - \int_0^\pi j_r 2\pi R^2 \cdot \sin \theta d\theta$$

$$= - 6\pi \rho_0 \mu \epsilon_0 R^2 \int_0^\pi \left(\frac{Q}{Q_{\max}} + \cos \theta \right) \sin \theta d\theta$$

$$= - 6\pi \rho_0 \mu \epsilon_0 R^2 \left(2 + 0 \right) \cdot \frac{Q}{Q_{\max}}$$

$$\frac{1}{Q_{\max}} \frac{dQ}{dt} = - \frac{\rho_0 \mu}{\epsilon_0} \frac{Q}{Q_{\max}}$$

$$(2) \quad -Q_{\max} < Q < Q_{\max}$$

$$\frac{dQ}{dt} = -6\pi \rho_0 \mu \epsilon_0 R^2 \cdot \int_{\theta_c}^{\pi} \left(\frac{Q}{Q_{\max}} + \cos \theta \right) \sin \theta d\theta$$

$$\theta_c = \arccos \left(-\frac{Q}{Q_{\max}} \right)$$

$$\cos \theta_c = -\frac{Q}{Q_{\max}}$$

$$\frac{1}{Q_{\max}} \frac{dQ}{dt} = -\frac{\rho_0 \mu}{2\epsilon_0} \cdot \left[\frac{Q}{Q_{\max}} (1 + \cos \theta_c) + \frac{1}{2} (\cos^2 \theta_c - 1) \right]$$

$$= -\frac{\rho_0 \mu}{2\epsilon_0} \left[\frac{Q}{Q_{\max}} \left(1 - \frac{Q}{Q_{\max}} \right) + \frac{1}{2} \left(\frac{Q^2}{Q_{\max}^2} - 1 \right) \right]$$

$$\frac{1}{Q_{\max}} \frac{dQ}{dt} = \frac{\rho_0 \mu}{4\epsilon_0} \left(1 - \frac{Q}{Q_{\max}} \right)^2$$

Solution QM1

$$a) \quad \hat{S}_n = \frac{\hbar}{2} \begin{bmatrix} \cos\theta & \sin\theta e^{-i\phi} \\ \sin\theta e^{i\phi} & -\cos\theta \end{bmatrix}$$

~~1~~ eigenvalues $\pm \hbar/2$

$$\hbar/2 \text{ has } \begin{bmatrix} \cos\theta/2 e^{-i\phi/2} \\ \sin\theta/2 e^{i\phi/2} \end{bmatrix} \quad \text{overall phase not determined}$$

b) let $|\psi\rangle$ be \uparrow

$$\langle \psi | \hat{S}_z | \psi \rangle = \frac{\hbar}{2} [\cos^2\theta/2 - \sin^2\theta/2] = 0$$

$$\Rightarrow \cos\theta/2 = \pm \sin\theta/2 \quad \text{say } + \text{ (will also work for } -)$$

$$\text{Now } |\psi\rangle = \frac{1}{\sqrt{2}} \begin{bmatrix} e^{-i\phi/2} \\ \pm e^{i\phi/2} \end{bmatrix}$$

$$\langle \psi | \hat{S}_x | \psi \rangle \text{ proportional to } e^{-i\phi} \pm e^{i\phi}$$

$$\langle \psi | \hat{S}_y | \psi \rangle \text{ proportional to } e^{-i\phi} - e^{i\phi}$$

Both can not be zero!

Solution QM 1 c)

$$U(t) = e^{-i\hat{H}t/\hbar}$$

$$\hat{H} = -g\mu B \frac{\hbar}{2} \sigma_y$$

$$\frac{\hat{H}}{\hbar} = -g\frac{\mu B}{2} \sigma_y$$

$$\gamma \equiv g\frac{\mu B}{2}$$

$$\frac{\hat{H}}{\hbar} = -\gamma \sigma_y$$

$$U(t) = e^{i\gamma t \sigma_y}$$

$$= \cos \gamma t + i \sigma_y \sin \gamma t$$

$$= \begin{bmatrix} \cos \gamma t & \sin \gamma t \\ -\sin \gamma t & \cos \gamma t \end{bmatrix}$$

$$|\psi(0)\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$|\psi(T)\rangle = \begin{bmatrix} \cos \gamma T \\ -\sin \gamma T \end{bmatrix}$$

$$\hat{S}_x = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

eigenvector with $\hbar/2$

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

probability

$$\frac{1}{2} (\cos(\gamma T) - \sin(\gamma T))^2$$

QM2 Solution

$$\hat{T}(d) = e^{i\hat{p}d/\hbar} \quad \leftarrow \text{translates by } d$$

want $\langle j | T(d) | 0 \rangle$

$$\hat{a} - \hat{a}^\dagger = \frac{1}{\sqrt{2\hbar\omega}} (i\hat{p} + i\hat{p}) = \frac{\sqrt{2}}{\sqrt{\hbar\omega}} i\hat{p}$$

$$\hat{p} = \frac{\sqrt{\hbar\omega}}{\sqrt{2}i} (\hat{a} - \hat{a}^\dagger) \quad \frac{i\hat{p}d}{\hbar} = \frac{\sqrt{\omega}}{\sqrt{\hbar}\sqrt{2}} d (\hat{a} - \hat{a}^\dagger) = r (\hat{a} - \hat{a}^\dagger)$$

$$r = \frac{\sqrt{\omega}}{\sqrt{\hbar}\sqrt{2}} d$$

$$e^{r(\hat{a} - \hat{a}^\dagger)} = ? \quad \hat{A} = -r\hat{a}^\dagger \quad \hat{B} = r\hat{a}$$

$$[\hat{A}, \hat{B}] = -r^2 [\hat{a}^\dagger, \hat{a}] = r^2$$

$$e^{(r\hat{a} - r\hat{a}^\dagger)} = e^{-r\hat{a}^\dagger} e^{r\hat{a}} e^{-\frac{1}{2}r^2}$$

$$\langle j | T(d) | 0 \rangle = e^{-\frac{1}{2}r^2} \langle j | e^{-r\hat{a}^\dagger} e^{r\hat{a}} | 0 \rangle$$

$$= e^{-\frac{1}{2}r^2} \langle j | e^{-r\hat{a}^\dagger} | 0 \rangle = e^{-\frac{1}{2}r^2} \sum_{l=0}^{\infty} \langle j | \frac{(-r\hat{a}^\dagger)^l}{l!} | 0 \rangle$$

$$= e^{-\frac{1}{2}r^2} \frac{(-r)^j}{\sqrt{j!}}$$

$$P(j) = e^{-r^2} \frac{r^{2j}}{j!}$$

$$b) |\psi(t)\rangle = e^{-i\hat{H}t/\hbar} |\psi(0)\rangle$$

$$= \sum_n e^{-i\omega(n+1/2)t} |n\rangle \langle n|\psi(0)\rangle$$

Probabilities will be the same for

$$t = \frac{2\pi}{\omega}, \frac{4\pi}{\omega}, \dots$$

c) Probability of finding any ~~any~~ energy is independent of t .

Stat Mech 1 Solution

$$dU = dQ - dW$$

Heat absorbed } work done by gas

Step 1. Isothermal $dU = 0$

$$dQ = dW$$

$$dQ = p dV = \frac{NkT}{V} dV$$

$$|Q_H| = NkT_H \ln(V_b/V_a)$$

step 3. $|Q_C| = NkT_C \ln(V_c/V_d)$

along 2 and 4 $dQ = 0$

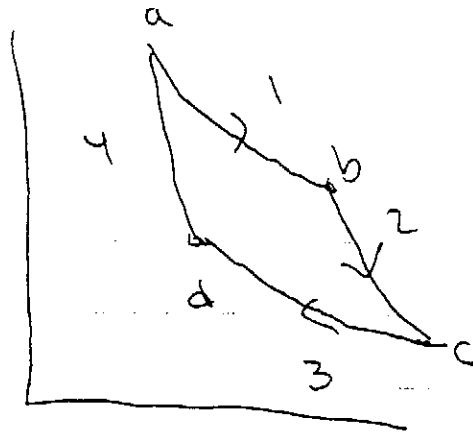
$$dU = -p dV$$

$$\frac{f}{2} Nk dT = -p dV$$

$$\frac{f}{2} (p dV + V dp) = -p dV$$

$$\frac{f}{2} V dp = \left(1 - \frac{f}{2}\right) p dV$$

$$\frac{dp}{p} = \alpha \frac{dV}{V}$$



Stat Mech 1 solution.

$$\frac{P_c}{P_b} = \left(\frac{V_c}{V_b}\right)^\alpha \quad \frac{P_a}{P_d} = \left(\frac{V_a}{V_d}\right)^\alpha$$

a and b have the same energy

$$P_a V_a = P_b V_b \quad \text{also} \quad P_c V_c = P_d V_d$$

$$\frac{P_a}{P_b} = \frac{V_b}{V_a}$$

$$\frac{P_c}{P_d} = \frac{V_d}{V_c}$$

$$\frac{P_a P_c}{P_b P_d} = \frac{V_b V_d}{V_a V_c}$$

$$\frac{P_c P_c}{P_b P_d} = \left(\frac{V_c V_a}{V_b V_d}\right)^\alpha$$

$$\frac{V_b V_d}{V_a V_c} = \frac{V_c^\alpha V_a^\alpha}{V_b^\alpha V_d^\alpha} \quad \frac{V_b^{\alpha+1}}{V_a^{\alpha+1}} = \frac{V_c^{\alpha+1}}{V_d^{\alpha+1}}$$

$$\Rightarrow \frac{V_b}{V_a} = \frac{V_c}{V_d}$$

$$e = \frac{-|Q_c|}{|Q_H|} = \frac{-T_c}{T_H} \quad \checkmark$$

Stat Mech 2 solutions

$$a) \frac{N}{2} = V \int_{\kappa < \kappa_f} \frac{d^3 \kappa}{(2\pi)^3} = V \int_0^{\kappa_f} \frac{4\pi \kappa^2 d\kappa}{(2\pi)^3} = \frac{V \kappa_f^3}{6\pi^2}$$

$$\kappa_f = (3\pi^2 n)^{1/3}$$

$$E_0 = 2V \int_{\kappa < \kappa_f} \frac{\hbar^2 \kappa^2}{2m} \frac{d^3 \kappa}{(2\pi)^3} = 2V \frac{\hbar^2}{2m} \frac{4\pi}{(2\pi)^3} \frac{\kappa_f^5}{5} = \frac{V \hbar^2 \kappa_f^5}{5\pi^2 2m}$$

$$\frac{E_0}{V} = \frac{3}{5} (3\pi^2)^{2/3} \frac{\hbar^2}{2m} n^{5/3}$$

$$b) \kappa_{f\pm} = (6\pi^2 n_{\pm})^{1/3}$$

$$c) \frac{E_{kin}}{V} = \frac{1}{10\pi^2} \frac{\hbar^2}{2m} (\kappa_{f+}^5 + \kappa_{f-}^5)$$

$$= \frac{1}{10\pi^2} \frac{\hbar^2}{2m} (6\pi^2)^{5/3} (n_+^{5/3} + n_-^{5/3})$$

$$= \frac{3}{5} (6\pi^2)^{2/3} \frac{\hbar^2}{2m} (n_+^{5/3} + n_-^{5/3})$$

$$= \frac{E_0}{V} + \frac{4}{3} (3\pi^2)^{2/3} \frac{\hbar^2}{2m} n^{-1/3} \delta^2 + \dots$$

$$d) \quad \frac{U}{V} = \alpha n_+ n_- = \alpha \left(\frac{n}{2} + \delta \right) \left(\frac{n}{2} - \delta \right)$$

$$= \alpha \frac{n^2}{4} - \alpha \delta^2$$

$$e) \quad \frac{E}{V} = \frac{E_0}{V} + \frac{\alpha n^2}{4} + \left[\frac{4}{3} (3\pi^2)^{2/3} \frac{\hbar^2 n^{5/3}}{2m} - \alpha \right] \delta^2 + \dots$$

$$\alpha_c = \frac{4}{3} (3\pi^2)^{2/3} \frac{\hbar^2 n^{5/3}}{2m}$$