

Recap: Introduced stress-energy tensor

$T^{\alpha\beta} \equiv$ flux of p^α in x^β direction

$T^{00} =$ energy density in some frame

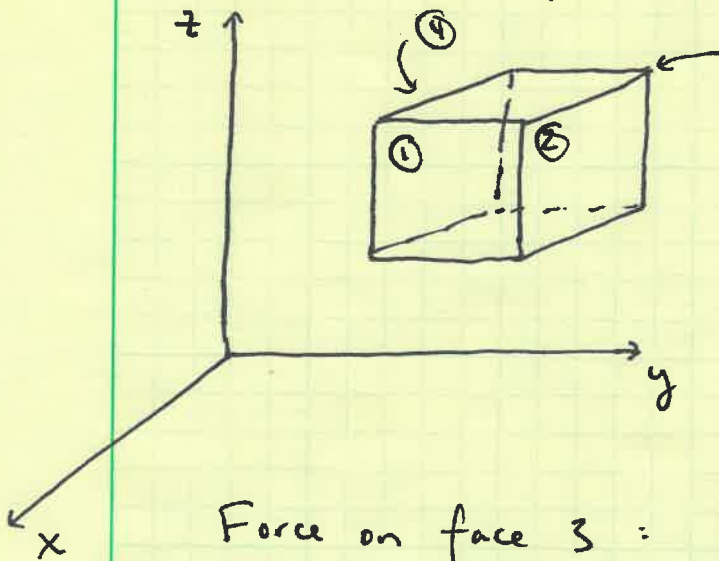
$T^{0j} =$ energy flux in x^j direction

$T^{i0} =$ density of momentum p^i

$T^{ij} =$ stress

Tensor is symmetric: $T^{\alpha\beta} = T^{\beta\alpha}$. If $T^{ij} \neq T^{ji}$, physically absurd situation could develop.

Consider cube of sides l embedded in $T^{\alpha\beta}$:



Force ~~on~~ on face 1:

$$\vec{F}_1 \equiv \{ T^{ix} l^2 \}$$

Force on face 2:

$$\vec{F}_2 \equiv \{ T^{iy} l^2 \}$$

Force on face 3: $\vec{F}_3 \cong -\vec{F}_1 \leftarrow$ exact as $l \rightarrow 0$

Force on face 4: $\vec{F}_4 \cong -\vec{F}_2$

Torques due to these forces:

$$\begin{aligned}\tau_1 \rightarrow \tau_1^z &= -x F_1^y = -x T^{yx} l^2 \\ &= -\frac{1}{2} T^{yx} l^3\end{aligned}$$

$$\tau_3 \rightarrow \tau_3^z = \tau_1^z$$

$$\begin{aligned}\tau_2 \rightarrow \tau_2^z &= y F_2^x = y T^{xy} l^2 \\ &= \frac{1}{2} T^{xy} l^3\end{aligned}$$

$$\tau_4 \rightarrow \tau_4^z = \tau_2^z$$

Add to find total: $\tau^z = l^3 (T^{xy} - T^{yx})$

Moment of inertia of cube: $I = \alpha (\rho l^3) l^2$
Coefficient of order unity

Angular acceleration of the cube:

$$\ddot{\Theta} = \tau^z / I$$

$$\propto (T^{xy} - T^{yx}) / l^2$$

In order for cube to not start spontaneously rotating, we must have $T^{xy} = T^{yx} \dots$

Considering other sides yields $T^{ij} = T^{ji}$.

Conservation of energy and momentum:

$$\partial_\alpha T^{\alpha\beta} = 0$$

Pick a particular frame, can break conservation principle into c of energy and c of m. In general, only a combined law makes sense.

$$\partial_\alpha T^{\alpha 0} = 0 \quad \text{conservation of energy}$$

$$\frac{\partial \rho}{\partial t} = - \frac{\partial T^{0i}}{\partial x^i}$$

↙
↘

rate of change of energy density
divergence of energy flux

Can be converted into an integral equation:

$$\frac{\partial}{\partial t} \int_{V^3} \rho d^3x = - \int_{\partial V^3} T^{0i} d\Sigma_i$$

\uparrow
 $dE/dA dt \rightarrow$ luminosity

$$\partial_\alpha T^{\alpha i} = 0 \quad \rightarrow \quad \text{conservation of momentum}$$

$$\rightarrow \frac{\partial T^{i0}}{\partial t} = - \frac{\partial T^{ij}}{\partial x^j} \quad (\text{or } \partial_t T^{i0} = - \partial_j T^{ij})$$

$$\partial_t \int_{V^3} T^{i0} d^3x = - \int_{\partial V^3} T^{ij} d\Sigma_j$$

Important example: "Perfect" fluid

No energy flow in rest frame

→ no heat transport

No lateral stress

→ no viscosity.

(Dry fluid)

Fluid is totally characterized by density ρ and pressure P :

There exists a frame in which

$$T^{\alpha\beta} = \begin{bmatrix} \rho & 0 & 0 & 0 \\ 0 & P & 0 & 0 \\ 0 & 0 & P & 0 \\ 0 & 0 & 0 & P \end{bmatrix}$$

(Notion of equation of state: relate P & ρ ,
 $P = P(\rho)$.)

Want to make the geometric construction of this. The ρ piece clearly comes from $\rho \vec{u} \otimes \vec{u}$, where \vec{u} is 4-vel of the "rest" frame. The P bits come from the projection tensor developed in part 1:

$$\bar{T} = \rho \vec{u} \otimes \vec{u} + P(\bar{\eta} + \vec{u} \otimes \vec{u})$$

$$\begin{aligned} \text{or } T_{\alpha\beta} &= \rho u_{\alpha} u_{\beta} + P(\eta_{\alpha\beta} + u_{\alpha} u_{\beta}) \\ &= P \eta_{\alpha\beta} + (\rho + P) u_{\alpha} u_{\beta} \end{aligned}$$

Another example: Point particle of rest mass m_0 moving on worldline $\vec{z}(\tau)$:

$$T_{\mu\nu} = m_0 \int d\tau u_\mu u_\nu \delta^4[\vec{x} - \vec{z}(\tau)]$$

$$\vec{u} = d\vec{z}/d\tau$$

Using $\delta^4[\vec{x} - \vec{z}(\tau)] = \delta[t - z^0(\tau)] \delta[x - z^i(\tau)] \dots$

plus the rule

$$\int f(x) \delta[g(x)] dx = \frac{f(x_0)}{|g'|_{x=x_0}}$$

where x_0 is defined such that $g(x_0) = 0$.

We can integrate this up to

$$T_{\mu\nu} = \frac{m_0 u_\mu u_\nu}{u^0} \delta^3[\vec{x} - \vec{z}(\tau)]$$

Another: $T_{EM}^{\mu\nu} = \frac{1}{4\pi} \left[F^{\mu\lambda} F^{\nu}_{\lambda} - \frac{1}{4} \eta^{\mu\nu} F^{\lambda\sigma} F_{\lambda\sigma} \right]$

$$\rightarrow T^{00} = \frac{\underline{E} \cdot \underline{E} + \underline{B} \cdot \underline{B}}{8\pi}$$

$$T^{0i} = \frac{(\underline{E} \times \underline{B})^i}{4\pi}$$

$$T^{ij} = \frac{1}{8\pi} \left[(\underline{E} \cdot \underline{E} + \underline{B} \cdot \underline{B}) \delta^{ij} - 2(E^i E^j + B^i B^j) \right]$$

Example: $\underline{E} = E^x \underline{e}_x$

$$T_{EM}^{\mu\nu} = \frac{(E^x)^2}{8\pi} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Attractive
"tension"

pressure

Follows from choosing Lagrangian density:

$$\mathcal{L} = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} + A_{\mu} J^{\mu} \quad [L = \int d^3x \mathcal{L}]$$

Then build an action: $S = \int dt L = \int d^4x \mathcal{L}$

$T_{\mu\nu}$ pops out by varying metric!

$$T_{\mu\nu} = \frac{-2}{\sqrt{\det(\eta_{\mu\nu})}} \frac{\delta S}{\delta g^{\mu\nu}}$$

Preclude to curvature: flat spacetime, but curvilinear coordinates.

$$(t, r, \phi, z) \quad x = r \cos \phi \quad y = r \sin \phi$$

Continue to use a coordinate basis:

$$\begin{aligned} d\vec{x} &= dx^\alpha \vec{e}_\alpha \\ &= dt \vec{e}_t + dr \vec{e}_r + d\phi \vec{e}_\phi + dz \vec{e}_z \end{aligned}$$

angle length

Not a normal basis! $|\vec{e}_\phi \cdot \vec{e}_\phi| \neq 1$.

Transformation matrix: $L^\alpha_{\bar{\mu}} \equiv \frac{\partial x^\alpha}{\partial x^{\bar{\mu}}}$ (Reserve $\Lambda^\alpha_{\bar{\mu}}$ for Lorentz transformation.)

Let barred be polar, unbarred be cartesian:

$$\frac{\partial x^\alpha}{\partial x^{\bar{\mu}}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \phi & \sin \phi & 0 \\ 0 & -r \sin \phi & r \cos \phi & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = L^\alpha_{\bar{\mu}}$$

$$\frac{\partial x^{\bar{\mu}}}{\partial x^\alpha} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \phi & -\sin \phi / r & 0 \\ 0 & \sin \phi & \cos \phi / r & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = L^{\bar{\mu}}_\alpha$$

Basis vectors:

$$\vec{e}_r = \cos\phi \vec{e}_x + \sin\phi \vec{e}_y = L^r_\alpha \vec{e}_\alpha$$

$$\vec{e}_\phi = -r\sin\phi \vec{e}_x + r\cos\phi \vec{e}_y = L^\alpha_\phi \vec{e}_\alpha$$

↳ Grows because the angle spans constant angle.

Metric: $g_{\alpha\beta} = \vec{e}_\alpha \cdot \vec{e}_\beta$

$$= \text{diag}(-1, 1, r^2, 1)$$

Reserve $\eta_{\alpha\beta}$ for $\text{diag}(-1, 1, 1, 1)$

Line element: $ds^2 = -dt^2 + dr^2 + r^2 d\phi^2 + dz^2$

Basis 1-forms: $\tilde{d}r = L^r_\alpha \tilde{d}x^\alpha = \cos\phi \tilde{d}x + \sin\phi \tilde{d}y$

$$\tilde{d}\phi = -\frac{\sin\phi}{r} \tilde{d}x + \frac{\cos\phi}{r} \tilde{d}y$$

Key place where this matters: Calculating derivatives. Need to include variation in basis vectors!

$$\frac{\partial \vec{e}_r}{\partial r} = 0$$

$$\frac{\partial \vec{e}_r}{\partial \phi} = \frac{\vec{e}_\phi}{r}$$

$$\frac{\partial \vec{e}_\phi}{\partial r} = \frac{\vec{e}_\phi}{r}$$

$$\frac{\partial \vec{e}_\phi}{\partial \phi} = -r \vec{e}_r$$

$$\vec{v} = v^\alpha \vec{e}_\alpha$$

$$\nabla \vec{v} = \partial_\beta (v^\alpha \vec{e}_\alpha) \tilde{w}^\beta$$

Components of tensor:

$$\frac{\partial \vec{v}}{\partial x^\beta} = \left(\frac{\partial v^\alpha}{\partial x^\beta} \right) \vec{e}_\alpha + v^\alpha \frac{\partial \vec{e}_\alpha}{\partial x^\beta}$$

$\partial \vec{e} / \partial x^\beta$ is something that we can write as linear combination of basis vectors:

$$\rightarrow \partial_\beta \vec{e}_\alpha = \frac{\partial \vec{e}_\alpha}{\partial x^\beta} = \Gamma_{\beta\alpha}^\mu \vec{e}_\mu$$

↳ "Christoffel Symbol"

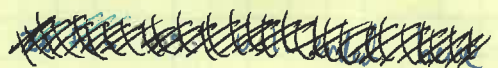
CAUTION: Schutz, MTW define this as $\Gamma_{\alpha\beta}^\mu$.

Carroll, Wald define as here. Turns out to be irrelevant - symmetric for coordinate bases. (will prove later.)

For polar coords, $\Gamma_{r\phi}^\phi = \Gamma_{\phi r}^\phi = 1/r$

$$\Gamma_{\phi\phi}^r = -r$$

All others - zero.



Return to derivative of vector:

$$\begin{aligned} \partial_\rho \vec{v} &= (\partial_\beta v^\alpha \vec{e}_\alpha + v^\alpha \Gamma_{\beta\alpha}^\mu \vec{e}_\mu) \\ &= (\partial_\beta v^\alpha \vec{e}_\alpha + v^\mu \Gamma_{\beta\mu}^\alpha \vec{e}_\alpha) \end{aligned}$$

$$\rightarrow \partial_\beta \vec{v} = \underbrace{(\partial_\beta v^\alpha + v^\mu \Gamma_{\beta\mu}^\alpha)}_{\text{The Covariant derivative}} \vec{e}_\alpha$$

$$\equiv \nabla_\beta v^\alpha \vec{e}_\alpha$$

$\nabla_\beta v^\alpha = \partial_\beta v^\alpha + v^\mu \Gamma_{\beta\mu}^\alpha$
← Not individually components of a tensor!
Free indices placed to agree w/LHS; dummy last.
Only sums is tensorial!

Components of tensor: $\nabla \vec{v} = \nabla_\beta v^\alpha \tilde{\omega}^\beta \otimes \vec{e}_\alpha$

Example application: divergence.

$$\begin{aligned} \nabla_\alpha v^\alpha &= \partial_\alpha v^\alpha + \Gamma_{\alpha\mu}^\alpha v^\mu \\ &= \partial_t v^t + \partial_z v^z + \partial_r v^r + \partial_\phi v^\phi + \Gamma_{\phi r}^\phi v^r \\ &= \partial_t v^t + \partial_z v^z + \partial_r v^r + \partial_\phi v^\phi + \frac{v^r}{r} \end{aligned}$$

Notice the term $\partial_\phi V^\phi$ - Is this dimensionally correct?

Consider the vector:

$$\vec{V} = V^\alpha \vec{e}_\alpha = V^t \vec{e}_t + V^r \vec{e}_r + V^\phi \vec{e}_\phi + V^z \vec{e}_z$$

Since $[\vec{e}_\phi]$ is length,

$[V^\phi] = [\vec{V}] / \text{length}$. So $\partial_\phi V^\phi$ is cool!

Derivs of other tensorial objects.

Scalars: No basis needed! So, no worries w complications:

$$\nabla_\alpha \phi = \partial_\alpha \phi$$

1-form: deduce by considering deriv of $\rho_\alpha A^\alpha \rightarrow$ scalar:

$$\begin{aligned} \nabla_\beta (\rho_\alpha A^\alpha) &= \partial_\beta (\rho_\alpha A^\alpha) \\ &= A^\alpha \partial_\beta \rho_\alpha + \rho_\alpha \partial_\beta A^\alpha \end{aligned}$$

Now write $\partial_\beta A^\alpha = \nabla_\beta A^\alpha - \Gamma_{\beta\mu}^\alpha A^\mu$:

$$\begin{aligned} \nabla_\beta (\rho_\alpha A^\alpha) &= A^\alpha \partial_\beta \rho_\alpha + \rho_\alpha \nabla_\beta A^\alpha - \rho_\alpha \Gamma_{\beta\mu}^\alpha A^\mu \\ &= \rho_\alpha \nabla_\beta A^\alpha + A^\alpha (\partial_\beta \rho_\alpha - \rho_\mu \Gamma_{\beta\alpha}^\mu) \end{aligned}$$

Now, require covariant deriv to obey Leibnitz rule:

$$\nabla_\beta (\rho_\alpha A^\alpha) = \rho_\alpha \nabla_\beta A^\alpha + A^\alpha \nabla_\beta \rho_\alpha$$

Compare:

$$\nabla_\beta \rho_\alpha = \partial_\beta \rho_\alpha - \Gamma_{\beta\alpha}^\mu \rho_\mu$$

From this, simple to find rule for 1-form derivatives:

$$\partial_\rho \tilde{\omega}^\alpha = -\Gamma_{\rho\mu}^\alpha \tilde{\omega}^\mu$$

Minus sign enforces

$$\langle \tilde{\omega}^\alpha, \tilde{e}_\rho \rangle = \delta^\alpha_\rho \rightarrow$$

(Can start with this, prove Leibnitz afterwards.)

generalize further:

$$\nabla_\beta T^{\mu\nu} = \partial_\beta T^{\mu\nu} + \Gamma_{\beta\alpha}^\mu T^{\alpha\nu} + \Gamma_{\beta\alpha}^\nu T^{\mu\alpha}$$

$$\nabla_\beta T_{\mu\nu} = \partial_\beta T_{\mu\nu} - \Gamma_{\beta\mu}^\alpha T_{\alpha\nu} - \Gamma_{\beta\nu}^\alpha T_{\mu\alpha}$$

$$\begin{aligned} \nabla_\beta T^{\mu\nu\dots}{}_{\rho\tau\dots} &= \partial_\beta T^{\mu\nu\dots}{}_{\rho\tau\dots} \\ &+ \Gamma_{\beta\alpha}^\mu T^{\alpha\nu\dots}{}_{\rho\tau\dots} + \Gamma_{\beta\alpha}^\nu T^{\mu\alpha\dots}{}_{\rho\tau\dots} \\ &- \Gamma_{\beta\rho}^\alpha T^{\mu\nu\dots}{}_{\alpha\tau\dots} - \Gamma_{\beta\tau}^\alpha T^{\mu\nu\dots}{}_{\rho\alpha\dots} \end{aligned}$$

Just go through and "correct" each index.

Definition $\partial_\beta \vec{e}_\alpha = \Gamma_{\beta\alpha}^\mu \vec{e}_\mu$ suggests we generate Christoffels by studying derivatives of basis vectors. Yuck.

Better way to get it: from the metric. Derivation will introduce a key property of tensor relationships:

A tensorial equation that holds in one representation must hold in ALL representations. CHANGING COORDINATES CANNOT CHANGE THE EQUATION!

Example application: "double gradient" of scalar.

Cartesian: $\nabla\nabla\phi = \partial_\alpha\partial_\beta\phi \tilde{\omega}^\alpha \otimes \tilde{\omega}^\beta$

↳ clearly symmetric!

general coordinates: $\nabla\nabla\phi = \nabla_\alpha\nabla_\beta\phi \tilde{\omega}^\alpha \otimes \tilde{\omega}^\beta$

Must be generally symmetric: $\nabla_\alpha\nabla_\beta\phi = \nabla_\beta\nabla_\alpha\phi$

→ $\cancel{\partial_\alpha\partial_\beta\phi} - \Gamma_{\alpha\beta}^\mu \partial_\mu\phi = \cancel{\partial_\beta\partial_\alpha\phi} - \Gamma_{\beta\alpha}^\mu \partial_\mu\phi$

→ $(\Gamma_{\alpha\beta}^\mu - \Gamma_{\beta\alpha}^\mu) \partial_\mu\phi = 0$

↳ Symmetry on Christoffels!

Important application: Gradient of metric.

$$\nabla \bar{g} = \partial_\gamma g_{\alpha\beta} \bar{\omega}^\alpha \otimes \bar{\omega}^\beta \otimes \bar{\omega}^\gamma = 0 \quad (\text{Cartesian})$$

$$= \nabla_\gamma g_{\alpha\beta} \bar{\omega}^\alpha \otimes \bar{\omega}^\beta \otimes \bar{\omega}^\gamma \quad \text{in general.}$$

We require $\nabla_\gamma g_{\alpha\beta} = 0$:

- Ⓘ $\nabla_\gamma g_{\alpha\beta} = \partial_\gamma g_{\alpha\beta} - \Gamma_{\gamma\alpha}^M g_{M\beta} - \Gamma_{\gamma\beta}^M g_{\alpha M} = 0$
- Ⓜ $\nabla_\alpha g_{\beta\gamma} = \partial_\alpha g_{\beta\gamma} - \Gamma_{\alpha\beta}^M g_{M\gamma} - \Gamma_{\alpha\gamma}^M g_{\beta M} = 0$
- Ⓝ $\nabla_\beta g_{\gamma\alpha} = \partial_\beta g_{\gamma\alpha} - \Gamma_{\beta\gamma}^M g_{M\alpha} - \Gamma_{\beta\alpha}^M g_{\gamma M} = 0$

Construct Ⓘ - Ⓜ - Ⓝ:

$$\begin{aligned} &\partial_\gamma g_{\alpha\beta} - \partial_\alpha g_{\beta\gamma} - \partial_\beta g_{\gamma\alpha} \\ &- \cancel{g_{M\beta} (\Gamma_{\gamma\alpha}^M - \Gamma_{\alpha\gamma}^M)} \rightarrow 0 \\ &+ g_{M\gamma} (\Gamma_{\alpha\beta}^M + \Gamma_{\beta\alpha}^M) \\ &+ \cancel{g_{M\alpha} (\Gamma_{\beta\gamma}^M - \Gamma_{\gamma\beta}^M)} \rightarrow 0 = 0 \end{aligned}$$

$$\begin{aligned} \rightarrow g_{M\gamma} \Gamma_{\alpha\beta}^M &= \frac{1}{2} (\partial_\alpha g_{\beta\gamma} + \partial_\beta g_{\gamma\alpha} - \partial_\gamma g_{\alpha\beta}) \\ &\equiv \Gamma_{\gamma\alpha\beta} \\ \Gamma_{\alpha\beta}^M &= g^{M\gamma} \Gamma_{\gamma\alpha\beta} \end{aligned}$$