

Recap: Introduced notion of parallel transport, needed to compare vectors/tensors at different points in manifold.

Two approaches

1. Rigorous: Noting that naive partial derivative ~~derivative~~ contaminates result with terms that don't leave us with a tensorial result, we define a derivative operator with a "connection":

$$\nabla_{\beta} A^{\alpha} = \partial_{\beta} A^{\alpha} + \Gamma^{\alpha}_{\beta\mu} A^{\mu}$$

Requirement that $\nabla_{\beta} g_{\mu\nu} = 0 \rightarrow \Gamma^{\mu}_{\beta\mu}$ is the Christoffel symbol defined earlier \rightarrow This derivative is just the covariant derivative!

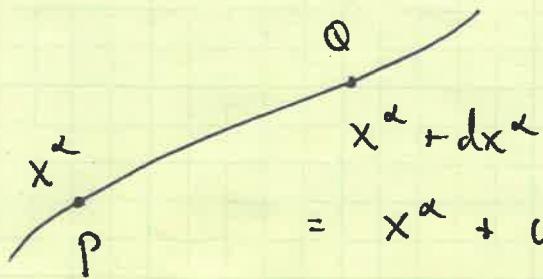
2. Physical: Go to LLF. Parallel transport reduces to just requiring components to slide along curve in manifold without change; find $\partial_{\beta} A^{\alpha}$ is good enough in LLF.

However: $\partial_{\beta} A^{\alpha} \equiv \nabla_{\beta} A^{\alpha}$ since partial & covariant are equivalent in LLF.

$\nabla_{\beta} A^{\alpha}$ is tensorial

What's tensorial in 1 frame is tensorial in all.

Another notion of transport:



$$u^\alpha = \frac{dx^\alpha}{d\lambda}, \text{ tangent}$$

in curve.

$$= x^\alpha + u^\alpha d\lambda$$

$$= (x')^\alpha \quad \cancel{\text{at point}}$$

Now, regard shift from P to Q as
a coordinate transformation:

$$A_{LT}^\alpha (P \rightarrow Q) = \text{vector } A^\alpha \text{ "transported" from P to Q}$$

$$= \frac{\partial(x')^\alpha}{\partial x^\beta} A^\beta$$

$$= (\delta_\beta^\alpha + (\partial_\beta u^\alpha) d\lambda) A^\beta (P)$$

$$\rightarrow A_{LT}^\alpha (P \rightarrow Q) = A^\alpha (P) + (\partial_\beta u^\alpha) A^\beta (P) d\lambda$$

The vector field at Q can be obtained by Taylor expansion:

$$A^\alpha (Q) = A^\alpha (x^\beta + dx^\beta)$$

$$= A^\alpha (x^\beta) + dx^\beta (\partial_\beta A^\alpha)|_P$$

$$= A^\alpha (P) + (u^\beta d\lambda) (\partial_\beta A^\alpha)$$

$$\text{Define: } \mathcal{L}_u A^\alpha = (A^\alpha (Q) - A_{LT}^\alpha (Q)) / d\lambda$$

$$= u^\beta \partial_\beta A^\alpha - A^\beta \partial_\beta u^\alpha$$

~~cancel~~

It's not hard to show that

$$\mathcal{L}_{\vec{u}} \vec{A}^\alpha = u^\beta \nabla_\beta A^\alpha - A^\beta \nabla_\beta u^\alpha$$

The connection coefficients just cancel out.

This means that this object - "the Lie derivative of \vec{A} along \vec{u} " - is ~~not~~ itself tensorial.

Common notation: $\mathcal{L}_{\vec{u}} \vec{A} = [\vec{u}, \vec{A}]$

Repeat exercise for a scalar: $\tilde{L}_{\vec{u}} \phi = u^\alpha \nabla_\alpha \phi$

1-form: Use $p_\alpha A^\alpha = \text{scalar}$, take Lie of total, find

$$\tilde{L}_{\vec{u}} p_\alpha = u^\beta \nabla_\beta p_\alpha + p_\beta \nabla_\alpha u^\beta$$

Tensor: $\tilde{L}_{\vec{u}} T^\alpha_\beta = u^\mu \nabla_\mu T^\alpha_\beta - T^m_\beta \nabla_\mu u^\alpha + T^\alpha_\mu \nabla_\beta u^m$

Utility: Consider a curve γ with tangent $\vec{u} = d\vec{x}/d\lambda$.

A tensor is "Lie transported" along \vec{u} if $\tilde{L}_{\vec{u}} (\text{tensor}) = 0$.
(Used a lot in fluids: \vec{u} defines flow line.)

If a tensor is Lie transported, then we can define the following coordinates: $x^0 = \lambda$ on the curve;
 $x^1, x^2, x^3 = \text{constant}$ on the curve.

$$\text{Then, } u^\alpha \equiv \frac{dx^\alpha}{d\lambda} \equiv \delta^\alpha_0. \rightarrow \partial_\mu u^\alpha = 0!$$

$$\text{Then, } \tilde{L}_{\vec{u}} (\text{tensor}) = 0 \rightarrow \frac{\partial (\text{tensor})}{\partial x^0} = 0$$

In these coordinates, the tensor is constant as we slide along the curve! Lie derivative gives us a covariant, frame independent way to describe a symmetry of a tensor field.

Example: suppose the tensor is the metric. Let us say there is some vector \vec{z} such that the metric is Lie transported along \vec{z} :

$$\mathcal{L}_{\vec{z}} g_{\alpha\beta} = 0$$

1. There exists a coordinate x^0 such that $\frac{\partial g_{\alpha\beta}}{\partial x^0} = 0$.

Metric is constant w.r.t. that coord. (Converse also holds: if the metric is constant wrt some coord, then a vector \vec{z} exists \Rightarrow such that the metric is Lie transported along \vec{z} .)

2. Expand the Lie derivative:

$$\mathcal{L}_{\vec{z}} g_{\alpha\beta} = 0 \rightarrow \vec{z}^\gamma \cancel{\nabla_\gamma g_{\alpha\beta}} + g_{\alpha\gamma} \nabla_\gamma \vec{z}^\beta + g_{\beta\gamma} \nabla_\gamma \vec{z}^\alpha = 0$$

$$\rightarrow \boxed{\nabla_\alpha \vec{z}_\beta + \nabla_\beta \vec{z}_\alpha = 0} \quad \text{"Killing's Eq"}$$

\vec{z} is called a Killing vector - describes a symmetry of spacetime.

(Note: used fact that metric commutes with ∇_α)

Tensor densities: Quantities that transform almost, but not quite, like tensors. off by a factor that looks like a determinant of a transformation matrix.

Most important tensor densities: Levi-Civita symbol + metric determinant.

$$\begin{aligned}\text{Levi-Civita: } \tilde{\epsilon}_{\alpha\beta\gamma\delta} &= +1 \quad \text{for } 0123 + \text{even perms.} \\ &= -1 \quad \text{for odd perms} \\ &= 0 \quad \text{any index repeated.}\end{aligned}$$

Theorem: For any 4×4 matrix,

$$\tilde{\epsilon}_{\alpha\beta\gamma\delta} M^\alpha_\mu M^\beta_\nu M^\gamma_\sigma M^\delta_\tau = \tilde{\epsilon}_{\mu\nu\sigma\tau} |M| \quad \begin{matrix} \uparrow \\ \text{Determinant of } M. \end{matrix}$$

Choose $M = \frac{\partial x^m}{\partial x^{m'}}$ - word trans matrix:

$$\tilde{\epsilon}_{\alpha'\beta'\gamma'\delta'} = \left| \frac{\partial x^m}{\partial x^{m'}} \right| \tilde{\epsilon}_{\alpha\beta\gamma\delta} \frac{\partial x^\alpha}{\partial x^{\alpha'}} \frac{\partial x^\beta}{\partial x^{\beta'}} \frac{\partial x^\gamma}{\partial x^{\gamma'}} \frac{\partial x^\delta}{\partial x^{\delta'}}.$$

Not a tensor trans. law! off by a factor of the Jacobian.

"Tensor density of weight 1."

Now look at metric:

$$g_{\alpha'\beta'} = \frac{\partial x^\alpha}{\partial x^{\alpha'}} \frac{\partial x^\beta}{\partial x^{\beta'}} g_{\alpha\beta}$$

$$\rightarrow g' = \left| \frac{\partial x^{\alpha'}}{\partial x^\alpha} \right|^{-2} g \quad \downarrow = \det(g_{\alpha\beta}).$$

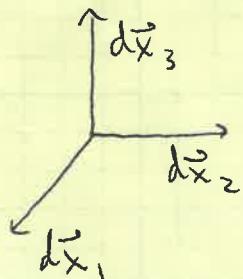
Tensor density of weight -2.

To convert a tensor density of weight w into a tensor, just multiply by $\begin{matrix} \lg |w| \\ \downarrow \text{abs val!} \end{matrix}$

Example: $\epsilon_{\alpha\beta\gamma\delta} = \sqrt{|g'|} \tilde{\epsilon}_{\alpha\beta\gamma\delta}$

$$\epsilon_{\alpha\beta\gamma\delta} = \frac{1}{\sqrt{|g'|}} \tilde{\epsilon}_{\alpha\beta\gamma\delta}$$

This is an important example: use these tensors to form covariant volume operators:



$$dV^4 = \sqrt{|g'|} \tilde{\epsilon}_{\alpha\beta\gamma\delta} dx_0^\alpha dx_1^\beta dx_2^\gamma dx_3^\delta$$

$$= \sqrt{|g'|} dx^0 dx^1 dx^2 dx^3$$

if basis is orthogonal.

Intuition: In 3-D, spherical words:

$$ds^2 = dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2$$

$$g_{\alpha\beta} = \text{diag}(1, r^2, r^2 \sin^2 \theta)$$

$$\rightarrow dr^3 = \sqrt{r^4 \sin^2 \theta} dr d\theta d\phi$$

Determinant of metric extremely useful! Gives a shortcut for computing certain Christoffels:

$$\Gamma^M_{\mu\alpha} = g^{\mu\beta} \Gamma_{\beta\mu\alpha}$$

$$= \frac{1}{2} g^{\mu\beta} (\cancel{\partial_\mu g_{\alpha\beta}} + \cancel{\partial_\alpha g_{\beta\mu}} - \cancel{\partial_\beta g_{\alpha\mu}}) \quad (\text{symm. of } g^{\mu\beta})$$

$$\rightarrow \Gamma^M_{\mu\alpha} = \frac{1}{2} g^{\mu\beta} \partial_\alpha g_{\mu\beta}$$

To show:

$$= \frac{1}{\sqrt{|g|}} \partial_\alpha (\sqrt{|g|}) \quad !$$

$$= \partial_\alpha (\ln \sqrt{|g|})$$

Proof: Consider some matrix M consider the following variation:

$$\begin{aligned}\delta \ln(\det M) &= \ln[\det(M + \delta M)] - \ln(\det M) \\ &= \ln\left[\frac{\det(M + \delta M)}{\det M}\right] \\ &= \ln\left[\det\left[1 + M^{-1} \cdot \delta M\right]\right]\end{aligned}$$

Last line, used $(\det M)^{-1} = \det M^{-1}$ and

$$(\det M)(\det N) = \det(M \cdot N)$$

Useful identity: If ϵ is a "small" matrix, then

$$\det[1 + \epsilon] \approx 1 + \text{Tr}(\epsilon) \quad (\text{where } \text{Tr}(\epsilon))$$

$$\begin{aligned}&= g^{\alpha\beta} \epsilon_{\alpha\beta} \equiv \epsilon^{\alpha}_{\alpha} \\ &\rightarrow \text{scalar.}\end{aligned}$$

$$\begin{aligned}\text{So, } \delta \ln(\det M) &= \ln[1 + \text{Tr}(M^{-1} \cdot \delta M)] \\ &\approx \text{Tr}(M^{-1} \cdot \delta M)\end{aligned}$$

$$\begin{aligned}\text{Now } M \rightarrow g_{\alpha\beta} : \delta \ln|g| &= \text{Tr}[g^{\mu\nu} \delta g_{\nu\mu}] \\ &= g^{\mu\nu} \delta g_{\nu\mu}\end{aligned}$$

$$\rightarrow \partial_\alpha \ln|g| = g^{\mu\nu} \partial_\alpha g_{\nu\mu}$$

$$\rightarrow \Gamma_{\mu\alpha}^\nu = \frac{1}{2} g^{\mu\nu} \partial_\alpha g_{\nu\mu}$$

$$= \partial_\alpha \ln|g|^{\frac{1}{2}}.$$

Utility: Divergence.

$$\begin{aligned}\nabla_\alpha A^\alpha &= \partial_\alpha A^\alpha + \Gamma_{\alpha\beta}^\alpha A^\beta = \partial_\alpha A^\alpha + \Gamma_{\beta\alpha}^\beta A^\alpha \\ &= \partial_\alpha A^\alpha + \frac{A^\alpha}{\sqrt{g}} \partial_\alpha (\sqrt{g})\end{aligned}$$

$$\rightarrow \nabla_\alpha A^\alpha = \frac{1}{\sqrt{g}} \partial_\alpha (\sqrt{g} A^\alpha)$$

Only involves partial derivatives!

Also gives a nice Gauss's Theorem:

$$\begin{aligned}\int_{V^4} (\nabla_\alpha A^\alpha) \sqrt{g} d^4x &= \int \partial_\alpha (\sqrt{g} A^\alpha) d^4x \\ &= \int_{\partial V^4} A^\alpha \sqrt{g} d\mathcal{I}_\alpha.\end{aligned}$$

Can we do this for tensors?

1. No: $\nabla_\alpha A^{\alpha\beta} = \partial_\alpha A^{\alpha\beta} + \Gamma_{\alpha\gamma}^\alpha A^{\gamma\beta} + \Gamma_{\beta\gamma}^\beta A^{\alpha\gamma}$

Nothing gains unless $A^{\alpha\beta}$ is antisymmetric - then 2nd term dies.

2. Not useful! $\nabla_\mu T^{\mu\nu}$ is a 4-vector. Can't integrate this up to make a conservation law: comparing data at different tangent spaces.